# On Contact Topology, Symplectic Field Theory and the PDE That Unites Them



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Slides available at:

http://www.homepages.ucl.ac.uk/~ucahcwe/publications.html#talks

Problem 1 (dynamics):

If  $H(q_1, p_1, \ldots, q_n, p_n)$  is a time-independent Hamiltonian and  $H^{-1}(c)$  is convex, does

$$\dot{q}_j = \frac{\partial H}{\partial p_j}, \qquad \dot{p}_j = -\frac{\partial H}{\partial q_j}$$

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# Problem 2 (topology):

Is a given closed manifold M the boundary of any compact manifold W?

How unique is W?

**Problem 3** (complex geometry / PDE): Given a Riemann surface  $\Sigma$  and complex manifold W, what is the space of holomorphic maps  $\Sigma \rightarrow W$ ? (Finite dimensional? Smooth? Compact?)

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**Problem 4** (mathematical physics): *How trivial is my TQFT?* 









**Definition.** A symplectic structure on a 2ndimensional manifold W is a system of local coordinate systems  $(q_1, p_1, \ldots, q_n, p_n)$  in which Hamilton's equations are invariant. It carries a natural volume form:

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 $\partial W$  is **convex** if it is transverse to a vector field Y that *dilates* the symplectic structure.

#### $M := \partial W$ convex $\rightsquigarrow$ contact structure

# $\xi \subset TM$ ,

a field of tangent hyperplanes that are "locally twisted" (*maximally nonintegrable*),



and transverse to the **Reeb** (i.e. Hamiltonian) vector field.

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**Example:**  $T^3 := S^1 \times S^1 \times S^1$ 



= boundary of  $T^2 \times \mathbb{D} = D^*T^2 \subset T^*T^2$ .

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When is  $(M_-, \xi_-) \prec (M_+, \xi_+)$ ? When is  $\emptyset \prec (M, \xi)$ ? (Is it *fillable*?)

**Theorem** (Eliashberg '89). If  $\xi_1$  and  $\xi_2$  are both overtwisted, then  $(M, \xi_1) \cong (M, \xi_2) \Leftrightarrow \xi_1$  and  $\xi_2$  are homotopic.



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**Theorem** (Gromov '85 and Eliashberg '89).  $\xi \text{ overtwisted} \Rightarrow (M, \xi) \text{ not fillable.}$ 

Non-overtwisted contact structures are called **"tight"**.

They are not fully understood.

## Conjecture.

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- $(M_-,\xi_-) \prec (M_+,\xi_+) \Rightarrow$  $\mathsf{AT}(M_{-},\xi_{-}) \leq \mathsf{AT}(M_{+},\xi_{+})$
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**Corollary**:  $(M_k, \xi_k) \xrightarrow{\text{contact surgery}} (M_\ell, \xi_\ell) \Rightarrow \ell \ge k.$ 



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 $(M,\xi)$  with Reeb vector field  $\rightsquigarrow$  $\mathcal{P} := \{ \text{periodic Reeb orbits on } M \}.$ 

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 $\mathcal{W} := \{ \text{formal power series } F(q_{\gamma}, p_{\gamma}, \hbar) \} \text{ with,}$  $[p_{\gamma}, q_{\gamma'}] = \delta_{\gamma, \gamma'} \hbar.$  $F \in \mathcal{W}, \text{ substitute } p_{\gamma} := \hbar \frac{\partial}{\partial q_{\gamma}} \rightsquigarrow \text{ operator}$  $D_F : \mathcal{A}[[\hbar]] \to \mathcal{A}[[\hbar]]$ 

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#### is a contact invariant.

Symplectic cobordism  $(M_-, \xi_-) \prec (M_+, \xi_+)$  $\rightsquigarrow$  natural map

$$H_*^{\mathsf{SFT}}(M_+,\xi_+) \to H_*^{\mathsf{SFT}}(M_-,\xi_-)$$

preserving elements of  $\mathbb{R}[[\hbar]]$ .

# Example

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# **Definition** (Latschev-W.).

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all "interesting" contact invariants vanish:

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(X,g) Riemannian manifold,  $f: X \to \mathbb{R}$  generic Morse function. Then singular homology

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where  $d_f$  counts rigid gradient flow lines,

$$\dot{x}(t) + \nabla f(x(t)) = 0.$$



SFT of  $(M, \xi = \ker \alpha)$ : " $\infty$ -dimensional Morse theory" for the contact action functional

$$\Phi: C^{\infty}(S^1, M) \to R: x \mapsto \int_{S^1} x^* \alpha,$$

with  $Crit(\Phi) = \{periodic \text{ Reeb orbits}\}.$ 

#### Gradient flow:

Consider 1-parameter families of loops  $\{u_s \in C^{\infty}(S^1, M)\}_{s \in \mathbb{R}}$  with

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For a symplectic cobordism W and Riemann surface  $\Sigma$ , consider *J*-holomorphic curves

$$u: \Sigma \setminus \{z_1, \ldots, z_n\} \to W$$

approaching Reeb orbits at the punctures.



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SFT compactness theorem:  $\overline{\mathcal{M}}_g(\Gamma^+, \Gamma^-) = \{J\text{-holomorphic buildings}\}$ 

 $\mathcal{H}^2$  counts the boundary of a 1-dimensional space  $\Rightarrow \mathcal{H}^2 = 0$ .

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$$D_{\mathcal{H}}(q_{\gamma_1} \dots q_{\gamma_k}) = \hbar^{k-1}$$
$$\Rightarrow [\hbar^{k-1}] = 0 \in H_*^{\mathsf{SFT}}(M, \xi)$$

 $\Rightarrow \mathsf{AT}(M,\xi) \leq k-1.$ 

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- Coarse classification—finitely many have AT(M, ξ) ≥ 2:
   V. Colin, E. Giroux and K. Honda, *Finitude homotopique et isotopique des structures de contact tendues*, Publ. Math. Inst. Hautes Études Sci. **109** (2009), no. 1, 245-293.

### Main reference

 Janko Latschev and Chris Wendl, Algebraic torsion in contact manifolds, Geom. Funct. Anal. 21 (2011), no. 5, 1144-1195, with an appendix by Michael Hutchings.

### Acknowledgment

Contact structure illustrations by Patrick Massot: http://www.math.u-psud.fr/~pmassot/



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http://www.homepages.ucl.ac.uk/~ucahcwe/publications.html#talks