# LaGO

### a Branch and Cut framework for nonconvex MINLPs

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# Lagrangian Global Optimizer

General purpose solver for sparse, block-separable, nonconvex MINLPs History:

2000 Development started by Ivo Nowak as a solver for nonconvex MIQQPs based on Lagrangian decomposition and semidefinite relaxation

2001-2004 Project funded by German Science Foundation: extension to MINLP solver

- Branch and Cut for MIQQPs
- heuristic Branch and Cut for nonconvex MINLPs
- start of Branch Cut and Price algorithm for MINLPs

Webpage: http://www.math.hu-berlin.de/~eopt/LaGO

Book: Ivo Nowak, Relaxation and Decomposition Methods for Mixed Integer Nonlinear Programming, Birkhäuser 2005 Stefan Vigerske LaGO - a Branch and Cut framework for nonconvex MINLPs

# Overview

Preprocessing

Branch and Cut algorithm

Cutting planes

Boxreduction

Numerical Results

Further developments

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# MINLP

We consider problems of the form

$$\begin{array}{ll} \text{minimize} & c^{T}x \\ \text{such that} & h_{i}\left(x\right) \leq 0, \qquad i \in I, \\ & h_{j}\left(x\right) = 0, \qquad j \in E, \\ & x_{k} \in \left\{0,1\right\}, \quad k \in B, \\ & x \in \left[\underline{x}, \overline{x}\right] \end{array}$$

 $-\infty < \underline{x}_i \le \overline{x}^i < \infty, i \in \{1, \dots, n\}, h \in C^2([\underline{x}, \overline{x}], \mathbb{R}^{|I|+|E|}), c \in \mathbb{R}^n$ LaGO interfaces problems via GAMS

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# Overview

#### Preprocessing

Branch and Cut algorithm

Cutting planes

Boxreduction

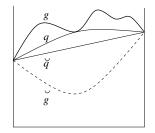
Numerical Results

Further developments

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# Preprocessing

- Investigation of problem structure (sparsity, block-separability, quadratic functions, convexity).
- Reduction of box  $[\underline{x}, \overline{x}]$ , determine bounding box for unbounded variables
- Initialization of linear relaxation:
  - 1. Nonquadratic nonconvex function g $\Rightarrow$  quadratic (nonconvex) underestimator q
  - 2. Quadratic nonconvex function q $\Rightarrow$  quadratic convex underestimator  $\breve{q}$
  - 3. Nonlinear convex function  $\Rightarrow$  linearization
  - 4. Binary conditions are dropped.



### Nonconvex quadratic underestimator

Let  $g \in C^2([\underline{x}, \overline{x}], \mathbb{R})$  be nonquadratic. Consider a sample set  $S \subseteq [\underline{x}, \overline{x}]$ .

We compute  $q(x) = x^T A x + b^T x + c$  by minimization of

$$\sum_{x \in S} \left( g\left( x \right) - q\left( x \right) \right) + \delta_1 \sum_{x \in S_1} \left| \nabla \left( g - q \right) \left( x \right) \right|_1 + \delta_2 \sum_{x \in S_2} \left| \nabla^2 \left( g - q \right) \left( x \right) \right|_1$$

such that  $q(x) \leq g(x)$  for all  $x \in S$ , where  $S_2 \subseteq S_1 \subseteq S$  and  $\delta_1, \delta_2 \geq 0$ .

- Can be formulated as a linear program.
- Sparsity of A and b determined by g(x).

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### Convex quadratic underestimator

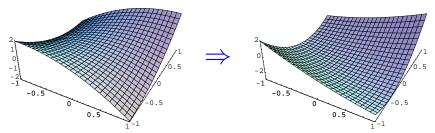
Let  $q(x) = x^T A x + b^T x + c$  be a quadratic nonconvex function.

A convex  $\alpha$ -underestimator (Adjiman and Floudas 1997) of q(x) is

$$\breve{q}(x) = q(x) + \sum_{i=1}^{n} \alpha_i (x_i - \underline{x}_i) (x_i - \overline{x}_i)$$

where

$$\alpha_i = -\lambda_1 \left( \mathsf{Diag} \left( \bar{x} - \underline{x} \right) \, A \, \mathsf{Diag} \left( \bar{x} - \underline{x} \right) \right) \, \left( \bar{x}_i - \underline{x}_i \right)^{-2}.$$



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Introduction Preprocessing Branch and Cut Cutting planes Boxreduction Numerical Results Further developments

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Preprocessing

#### Branch and Cut algorithm

Cutting planes

Boxreduction

Numerical Results

Further developments

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# Main Loop

Denote by  $\hat{x}$  a solution of the linear relaxation.

- 1. Take node with lowest lower bound from Branch and Bound tree.
- 2. Upper bounds: Start local search (with fixed binary variables) from  $\hat{x}$  (rounded) (GAMS/NLP-Solver or IPOPT)

# Main Loop

Denote by  $\hat{x}$  a solution of the linear relaxation.

- 1. Take node with lowest lower bound from Branch and Bound tree.
- 2. Upper bounds: Start local search (with fixed binary variables) from  $\hat{x}$  (rounded) (GAMS/NLP-Solver or IPOPT)
- 3. Branch: select a variable x<sub>i</sub>
  - whose binary condition is mostly violated by  $\hat{x}$
  - or: where  $g(x) \leq 0$  is mostly violated by  $\hat{x}$ ,  $\frac{\partial}{\partial x_i}g(\hat{x})$  is large, and the box of  $x_i$  hasn't been reduced very much so far
  - or: whose box is least reduced

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  - or: whose box is least reduced
- 4. Bound: for each child node
  - 4.1 Generate and update cuts
  - 4.2 Update the box
  - 4.3 Solve the linear relaxation (CPLEX or COIN/Clp)
  - 4.4 Put nodes into tree

5. Prune: Prune nodes which lower bound exceeds upper bound

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Introduction Preprocessing Branch and Cut Cutting planes Boxreduction Numerical Results Further developments

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Preprocessing

Branch and Cut algorithm

### Cutting planes

Boxreduction

Numerical Results

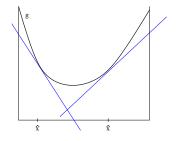
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# Linearization Cuts

reference point  $\hat{x}$ , convex constraint  $g(x) \leq 0$ 

$$g(\hat{x}) + \nabla g(\hat{x})(x - \hat{x}) \leq 0$$



Linearizations of convexified functions

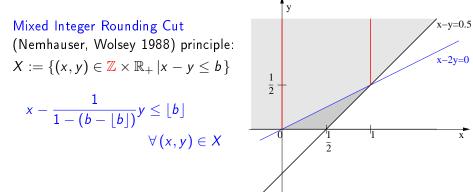
$$g(x) := q(x) + \sum_{i=1}^{n} \alpha_i (x_i - \underline{x}_i) (x_i - \overline{x}_i)$$

can easily be updated after a reduction of the box  $[\underline{x}, \overline{x}]$ .

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## Mixed Integer Rounding Cuts

- Linear relaxation solved via COIN Open Solver Interface
- COIN Cut Generator Library provides several types of cuts to cut off a nonintegral solution of the relaxation



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# Overview

Preprocessing

Branch and Cut algorithm

Cutting planes

#### Boxreduction

Numerical Results

Further developments

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## Boxreduction based on intervalarithmetic

• Consider a constraint

$$g(x,y):=h(x)+y\leq 0,$$

i.e.,  $y \leq -h(x)$ , and let

$$\left[\underline{h},\overline{h}\right] := -h\left([\underline{x},\overline{x}]\right).$$

• If  $\bar{h} \leq \bar{y}$ , set

$$\bar{y} := \bar{h}$$

and proceed with other constraints depending on y.

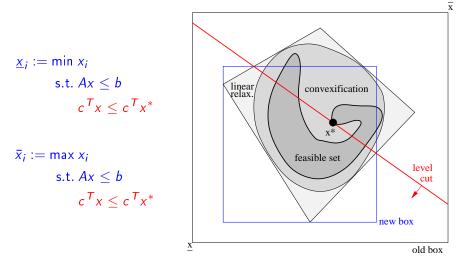
- Does not rely on relaxations. Easy and fast to compute.
- Interval arithmetic provided by GAMS-interface and FILIB++.

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# Boxreduction based on linear relaxation

Consider a linear relaxation with constraints  $Ax \leq b$ .

Let  $x^*$  be the best solution found so far.



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Preprocessing

Branch and Cut algorithm

Cutting planes

Boxreduction

Numerical Results

Further developments

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# GAMS MINLPLib and GlobalLib

- at most 1000 variables and no integrality conditions except for binary ⇒ 33 MIQQPs, 72 (nonquadratic) MINLPs, 166 QQPs
- timelimit: 1 hour
- NLP subsolver: CONOPT; LP subsolver: CPLEX 10.0

	MIQQPs	MINLPs
number of models	33	72
best known optimal solution found	21	41
nonoptimal solution found	5	9
unsuccessful Branch & Cut search	7	13
failure in preprocessing	0	9

Pentium IV 3.00 Ghz, 1 GB RAM, Linux 2.16.11

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# LaGO vs. BARON on MIQQPs

LaGO and BARON 7.5 on MIQQPs from MINLPLib:

		optimal value		
	Total	LaGO better	same	BARON better
BARON fail, LaGO not	3	3		
LaGO faster	1		1	2
both solvers the same	7		5	
BARON faster	15	2	12	1
LaGO fail, BARON not	2			2
LaGO and BARON fail	5		5	
Total	33	5	23	5

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# LaGO vs. BARON on MINLPs

LaGO and BARON 7.5 on (nonquadratic) MINLPs from MINLPLib:

		optimal value		
	Total	LaGO better	same	BARON better
BARON fail, LaGO not	5	5		
LaGO faster	10	1	4	5
both solvers the same	10	1	9	
BARON faster	25	3	18	4
LaGO fail, BARON not	11			11
LaGO and BARON fail	11		11	
Total	72	10	38	20

LaGO stops branching when all binary variables are fixed

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# LaGO vs. BARON on QQPs

running LaGO and BARON 7.5 on QQPs from GlobalLib:

		optimal value		
	Total	LaGO better	same	BARON better
BARON fail, LaGO not	1	1		
LaGO faster	11	1	9	1
both solvers the same	90		89	1
BARON faster	61		61	
LaGO fail, BARON not	3			3
Total	166	2	159	5

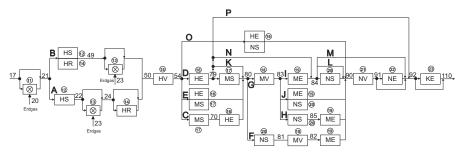
# Optimizing the design of a complex energy conversion plant

2001-2004: project funded by German Science Foundation

Institute for <mark>Energy Engineering</mark> (Technical University Berlin) T. Ahadi-Oskui, F. Cziesla, G. Tsatsaronis

Institute for Mathematics (Humboldt University Berlin) H. Alperin, I. Nowak, S. Vigerske

- Model: superstructure of a combined-cycle-based cogeneration plant
- Simultaneous structural and process variable optimization



picture: exhaust gas path through heat-recovery steam generator

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# Model of a complex energy conversion plant

- superstructure for electric power output of  $\leq$  400 MW and process steam production of  $\leq$  500 t/h
- degrees of freedom: 27 structural and 48 process variables
- constraints:
  - logic of the superstructure (connecting binary variables)
  - thermodynamic behavior (highly nonlinear), mass+energy balances
  - purchase equipment costs
- objective: total cost for cogeneration plant investment cost, operation and maintenance cost, taxes and insurances,...
- MINLP model: 1308 variables (44 binary) and 1659 constraints
- GAMS MINLPLib models super1, super2, super3, and super3t

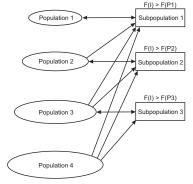
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# Distributed genetic algorithm

- individual = set of decision variables
- fitness obtained by simulation of the superstructure

HSC-GA: hierarchical social competition algorithm:

- handling several populations in parallel
- organized by fitness of inhabitants
- individuals from lower population can move into subpopulation at higher level
- after evolving for some time, they migrate into higher population



# Optimization of the superstructure

- HSC-GA and LaGO run for 24 hours
  - HSC-GA:  $\approx$  20000 generations
  - LaGO: pprox 30000 Branch and Bound iterations

demand	method	efficiency	cost
electric power: 300 MW	LaGO	56.7%	12674 Euro/h
	HSC-GA	55.4%	12774 Euro/h
electric power: 290 MW	LaGO	68.5%	13424 Euro/h
process steam: 150 t/h	HSC-GA	67.7%	13399 Euro/h
electric power: 400 MW	LaGO	58.6%	16771 Euro/h
	HSC-GA	58.7%	17229 Euro/h

Turang Ahadi-Oskui (2006): Optimierung des Entwurfs komplexer Energieumwandlungsanlagen, Fortschritts-Berichte VDI, Reihe 6, Nr. 543.

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Preprocessing

Branch and Cut algorithm

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#### Further developments

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### Mixed-integer linear relaxation

- MIP solver are fast and robust today.
- Replace linear relaxation by a mixed-integer linear relaxation.

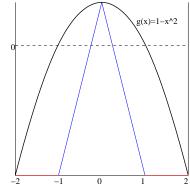
Allows use of intervalgradient cuts (Boddy, Johnson 2003 for MIQQPs): Intervalgradient of g:

$$\left[\underline{d}, \overline{d}\right] := \nabla g\left([\underline{x}, \overline{x}]\right)$$

 $(\nabla g(x) \in \left[\underline{d}, \overline{d}\right] \ \forall x \in [\underline{x}, \overline{x}])$ 

Intervalgradient cut w.r.t.  $\hat{x} \in [\underline{x}, \overline{x}]$ :

$$g(\hat{x}) + \min_{d \in [\underline{d}, \overline{d}]} d^{T}(x - \hat{x}) \leq 0$$



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# Intervalgradient Cuts

Intervalgradient cut w.r.t.  $\hat{x} \in [\underline{x}, \overline{x}]$ :  $[\underline{d}, \overline{d}] := \nabla g([\underline{x}, \overline{x}])$ 

$$g(\hat{x}) + \min_{d \in [\underline{d}, \overline{d}]} d^{T}(x - \hat{x}) \leq 0$$

Reformulation:

$$g(\hat{x}) + \underline{d}^{T}y^{+} - \overline{d}^{T}y^{-} \leq 0$$
  

$$x - \hat{x} = y^{+} - y^{-}$$
  

$$0 \leq y_{i}^{+} \leq z_{i}(\bar{x}_{i} - \hat{x}_{i}), \quad i = 1, ..., n$$
  

$$0 \leq y_{i}^{-} \leq (1 - z_{i})(\hat{x}_{i} - \underline{x}_{i}), \quad i = 1, ..., n$$
  

$$z_{i} \in \{0, 1\}, \quad i = 1, ..., n$$

- applied to original formulation of MINLP, independent of relaxations
- currently implemented in LaGO with relaxed binary conditions

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## Further improvements...

- reliable underestimators of nonquadratic nonconvex functions
- support of integer variables
- branching rules

. . .

node selection rules

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- reliable underestimators of nonquadratic nonconvex functions
- support of integer variables
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# Thank you!

#### http://www.math.hu-berlin.de/~eopt/LaGO

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