

**SOMMERSEMESTER 2016 - HÖHERE ANALYSIS II  
LINEARE PARTIELLE DIFFERENTIALGLEICHUNGEN**

**Homework #4 Solutions**

**Problem 1.** Suppose that  $\Omega \subset \mathbb{R}^d$  is of class  $C^1$ . Fix  $\underline{x} \in \partial\Omega$ . Then there exists a neighborhood  $\mathcal{U}(\underline{x})$  and a function  $g \in C^1$  such that

$$\partial\Omega \cap \mathcal{U}(\underline{x}) = \{x \in \mathcal{U}(\underline{x}) : x_d = g(x')\} \quad \text{and} \quad \Omega \cap \mathcal{U}(\underline{x}) = \{x \in \mathcal{U}(\underline{x}) : x_d > g(x')\}.$$

Let  $\chi_\Omega$  be the characteristic function of  $\Omega$ . Prove that

$$\partial_j \chi_\Omega = -\nu_j dS \quad \text{for all } x \in \mathcal{U}(\underline{x})$$

(and hence for all  $x \in \mathbb{R}^d$ ). Here  $\nu$  denotes the the exterior unit normal vector field along  $\partial\Omega$  and  $dS$  denotes the surface measure on  $\partial\Omega$ . Hint: In  $\mathcal{U}(\underline{x})$  we have

$$\chi_\Omega(x) = \lim_{\varepsilon \rightarrow 0} h\left(\frac{x_d - g(x')}{\varepsilon}\right) \quad \text{as } \varepsilon \rightarrow 0,$$

pointwise and in the sense of distributions, where  $h \in C^\infty(\mathbb{R}, [0, 1])$  satisfies  $h(t) = 1$  for all  $t \in (1, \infty)$  and  $h(t) = 0$  for all  $t \in (-\infty, 0)$ .

*Proof.* Recall that

$$\nu(x') = \frac{(\nabla g(x'), -1)}{\sqrt{1 + |\nabla g(x')|^2}}.$$

Compute, using the chain rule

$$\partial_j h\left(\frac{x_d - g(x')}{\varepsilon}\right) = h'\left(\frac{x_d - g(x')}{\varepsilon}\right) \frac{\nu_j(x') \sqrt{1 + |\nabla g(x')|^2}}{\varepsilon}, \quad \text{for } j = 1, \dots, d.$$

The distributional derivative of  $\chi_\Omega$  can be computed as follows. Choose  $\varphi \in C_0^\infty(\mathcal{U}(\underline{x}))$ . Then, relying on Proposition 3.7 and using the change of variables  $s = (x_d - g(x'))/\varepsilon$ , one obtains

$$\begin{aligned} \partial_j \chi(\varphi) &= - \lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^d} h'\left(\frac{x_d - g(x')}{\varepsilon}\right) \frac{\nu_j(x') \sqrt{1 + |\nabla g(x')|^2}}{\varepsilon} \varphi(x) dx \\ &= - \lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^{d-1}} \frac{1}{\varepsilon} \left\{ \int_{\mathbb{R}} h'\left(\frac{x_d - g(x')}{\varepsilon}\right) \varphi(x', x_d) dx_d \right\} \nu_j(x') \sqrt{1 + |\nabla g(x')|^2} dx' \\ &= - \lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^{d-1}} \left\{ \int_0^1 h'(s) \varphi(x', \varepsilon s + g(x')) ds \right\} \nu_j(x') \sqrt{1 + |\nabla g(x')|^2} dx' \\ &= - \lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^{d-1}} \varphi(x', \varepsilon + g(x')) \nu_j(x') \sqrt{1 + |\nabla g(x')|^2} dx' \\ &\quad + \lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^{d-1}} \left\{ \int_0^1 h(s) \frac{d}{ds} \varphi(x', \varepsilon s + g(x')) ds \right\} dx' \\ &= - \int_{\mathbb{R}^{d-1}} \varphi(x', g(x')) \nu_j(x') \sqrt{1 + |\nabla g(x')|^2} dx' = - \int_{\partial\Omega} \varphi(x) \nu_j(x) dS(x) \end{aligned}$$

This shows that

$$\partial_j \chi_\Omega = -\nu_j dS \quad \text{in } \mathcal{D}'(\mathcal{U}(\underline{x})) .$$

Of course, since the choice of  $\underline{x}$  was arbitrary, one obtains

$$\partial_j \chi_\Omega = -\nu_j dS \quad \text{in } \mathcal{D}'(X)$$

where  $X \subset \mathbb{R}^d$  is open and  $X \cap \partial\Omega$  is the graph of a  $C^1$ -function. Using a partition of unity, one obtains

$$\partial_j \chi_\Omega = -\nu_j dS \quad \text{in } \mathcal{D}'(\mathbb{R}^d) .$$

□

**Problem 2.** Use the result of problem above to give a proof of Theorem 3.3. (Gauss's Theorem).

*Proof.* Let  $f \in C^1(\mathbb{R}^d)$ . Then using the solution to the problem above

$$\int_{\Omega} \partial_j f dx = \int_{\mathbb{R}^d} \chi_\Omega(x) \partial_j f(x) dx = -\partial_j \chi(f) = (\nu_j dS)(f) = \int_{\partial\Omega} f(x) \nu_j(x) dS(x) .$$

Technically, a distribution is a linear functional on a function in  $\mathcal{D}(\mathbb{R})$ . However, the distributions  $\chi$  and  $dS$  are of order zero and can view as linear functionals on the continuous functions. □

**Problem 3.** a.) Given is a compact set  $K \subset U$  where  $U$  is an open set in  $\mathbb{R}^d$ . Use Theorem 3.9 to establish the existence of a function  $\eta \in C_0^\infty(U)$  which satisfies  $\eta(x) = 1$  for all  $x \in K$ .

b.) Use part a.) to establish the existence of a partition of unity  $\{\eta_j\}_{j=1}^m$  subordinate to the finite open cover  $\{U_j\}_{j=1}^m$  of  $\bar{\Omega} \subset \mathbb{R}^d$ , that is, a family of functions  $\eta_j \in C_0^\infty(\mathbb{R}^d)$  with  $\text{supp } \eta_j \subset U_j$ ,  $0 \leq \eta_j \leq 1$  for  $j = 1, 2, \dots, m$ , and  $\sum_{j=1}^m \eta_j = 1$  for all  $x \in \Omega$ . You may assume that  $\Omega$  is an open and bounded set and that each  $U_j$  is bounded,  $j = 1, 2, \dots, m$ .

*Solution.* a.) There exists  $\varepsilon > 0$  such that  $K^{3\varepsilon} \subset U$  where  $K^\varepsilon = \{x \in \mathbb{R}^d : \text{dist}(\partial K, x) \leq \varepsilon\}$ . Now set  $\eta = \psi_\varepsilon * \chi_{K^\varepsilon}$  where  $\psi_\varepsilon$  is the family of Friedrichs mollifiers defined in the lecture and  $\chi_A$  is the characteristic function of  $A \subset \mathbb{R}^d$ . Note that for  $x \in \mathbb{R}^d \setminus K^{2\varepsilon}$  we have

$$\eta(x) = \int_{\mathbb{R}^d} \psi_\varepsilon(y-x) \chi_{K^\varepsilon}(y) dy = \int_{K^\varepsilon} \psi_\varepsilon(y-x) dy = 0$$

since  $\psi_\varepsilon(z) = 0$  for  $|z| \geq \varepsilon$ . This proves  $\eta \in C_0^\infty(U)$ . Furthermore, for  $x \in K$  we have

$$\eta(x) = \int_{\mathbb{R}^d} \psi_\varepsilon(y-x) \chi_{K^\varepsilon}(y) dy = \int_{K^\varepsilon} \psi_\varepsilon(y-x) dy = \int_{\mathbb{R}^d} \psi_\varepsilon(y-x) dy = 1 ,$$

since for  $y \notin K^\varepsilon$  and we have  $\psi_\varepsilon(y-x) = 0$ .

b.) At first one constructs a new open cover  $V_j$  of  $\bar{\Omega}$  with the property that  $\bar{V}_j \subset U_j$ . This is done as follows. Set

$$F_1 = \bar{\Omega} \setminus \bigcup_{j=2}^m U_j \subset U_1 .$$

Note that  $F_1$  is a compact set. Hence, there exists an open set  $V_1 \supset F_1$  such that  $\bar{V}_1 \subset U_1$ . Similarly one finds the open sets  $V_2, \dots, V_m$ . Set

$$F_k = \bar{\Omega} \setminus \left[ \bigcup_{j=1}^{k-1} V_j \cup \bigcup_{j=k+1}^m U_j \right] \subset U_k, \quad \text{for } k = 2, \dots, m.$$

and choose open sets  $V_j \subset U_j$  such that  $\bar{V}_j \subset U_j$  and  $F_j \subset V_j$  for  $j = 2, \dots, m$ . Note that the definition of  $F_k$  requires only the knowledge of  $V_1, \dots, V_{k-1}$ .

According to part a.) there exist functions  $\phi_j$  such that  $\phi \in C_0^\infty(U_j)$ ,  $0 \leq \phi_j \leq 1$  for  $j = 1, 2, \dots, m$ , and  $\phi(x) = 1$  for all  $x \in \bar{V}_j$ . Since  $\bar{\Omega} \subset \bigcup_{k=1}^m V_k$ , there exists an open set  $V \supset \bar{\Omega}$  such that  $V \subset \bigcup_{k=1}^m V_k$ . Using part a.) there exists a function  $\phi \in C_0^\infty(\bigcup_{k=1}^m V_k)$  with  $0 \leq \phi \leq 1$  and  $\phi(x) = 1$  for all  $x \in V$ . Finally, the functions  $\phi_j$  and  $\phi$  can be considered as functions in  $C_0^\infty(\mathbb{R}^d)$ .

Set now

$$\eta_j(x) = \begin{cases} \frac{\phi_j(x)}{(1 - \phi(x)) + \sum_{k=1}^m \phi_k(x)} & \text{for } x \in U_j, \\ 0 & \text{for } x \notin U_j, \end{cases} \quad \text{for } j = 1, 2, \dots, m.$$

and observe that  $\eta_j \in C_0^\infty(\mathbb{R}^d)$ ,  $0 \leq \eta_j \leq 1$  for  $j = 1, 2, \dots, m$ , and that  $\sum_{j=1}^m \eta_j(x) = 1$  for

all  $x \in \Omega$ . The introduction of the function  $\phi$  ensures that no division by zero occurs in this definition.

Note that this construction works - mutatis mutandis - in the situation where each  $U_j$  is a bounded, open subset of  $\Omega$  such that  $\bar{U}_j \subset \Omega$ , every compact subset of  $\Omega$  intersects only finitely many  $U_j$  and

$$\Omega = \bigcup_{j=1}^{\infty} U_j.$$

For details we refer to the book by Renardy and Rogers [1, Theorem 5.6]. This has been used in the proof of Theorem 3.13.

## REFERENCES

- [1] Michael Renardy and Robert C. Rogers. *An introduction to partial differential equations*, volume 13 of *Texts in Applied Mathematics*. Springer-Verlag, New York, 1993.