

MODULAR FAMILIES OF ELLIPTIC LONG-RANGE SPIN CHAINS FROM FREEZING

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ABSTRACT. We consider the construction of quantum-integrable spin chains with q -deformed long-range interactions by ‘freezing’ integrable quantum many-body systems with spins. The input is a spin-Ruijsenaars system along with an equilibrium configuration of the underlying spinless classical Ruijsenaars–Schneider system. For a distinguished choice of equilibrium, the resulting long-range spin chain has a real spectrum and admits a short-range limit, providing an integrable interpolation from nearest-neighbour to long-range interacting spins.

We focus on the elliptic case. We first define an action of the modular group on the spinless elliptic Ruijsenaars–Schneider system to show that, for a fixed elliptic parameter, it has a whole modular family of classical equilibrium configurations. These typically have constant but nonzero momenta. Then we use the setting of deformation quantisation to provide a uniform framework for freezing elliptic spin-Ruijsenaars systems at any classical equilibrium whilst preserving quantum integrability. As we showed in previous work, the results include the Heisenberg, Inozemtsev and Haldane–Shastry chains along with their xxz-like q -deformations (face type), or the antiperiodic Haldane–Shastry chain of Fukui–Kawakami, its elliptic generalisation of Sechin–Zotov, and their completely anisotropic q -deformations due to Matushko–Zotov (vertex type).

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1. INTRODUCTION

Integrable spin systems with long-range interactions provide theoretical laboratories to study physical phenomena such as fractional statistics and long-range order [Hal91, Tho69, HT13]. Unlocking this potential, however, requires understanding the exact underlying mathematical structures. The best-understood member of the long-range family is the Haldane–Shastry chain [Hal88, Sha88]. Its integrability descends from that of a related quantum many-body system, the trigonometric Calogero–Sutherland system with spins, through a procedure called *freezing* [Pol93]. This enables one to leverage the rich algebraic structure of that quantum many-body system [BGHP93], see also [LS24]. Freezing relies on a decoupling of the dynamical degrees of freedom (coordinates and momenta), which become classical, from the spins, which remain fully quantum mechanical. As suggested in [LRS24], this situation is analogous to the Born–Oppenheimer approximation, in which electrons moving around atomic nuclei are viewed as quantum-mechanical particles moving in a classical background given by the (much more massive) nuclei. Similarly, the Haldane–Shastry chain comprises quantum-mechanical spins interacting in a background governed by the classical trigonometric Calogero–Moser–Sutherland system. This situation extends to the q -deformed level, connecting the spin-Ruijsenaars–Macdonald system with the XXZ-type generalisation of the Haldane–Shastry chain [Ugl95, Lam18, LPS22].

For *elliptic* long-range spin chains, a recent surge of activity has started to fill in several long-standing gaps in the understanding of their integrability. For the Inozemtsev chain [Ino90], which interpolates between the Heisenberg XXX and Haldane–Shastry chains, it has long been known that its exact eigenfunctions are built from those of the scalar elliptic Calogero–Sutherland system [Ino95]. Our more recent reformulation in terms of physically motivated quantities [KL22] connects this solution directly to the exact (Bethe-ansatz/Jack) wave functions of the limiting spin chains, paving the way for a direct comparison of their integrable structures. A set of conserved quantities was proposed in [Ino96], but their mutual commutativity, and hence the integrability of Inozemtsev chain, remained an open problem for a long time. In [Cha24], Chalykh addressed it by constructing a hierarchy of commuting higher hamiltonians using elliptic Dunkl operators [BFV94] and freezing.

In this paper, we zoom in on freezing at the q -deformed elliptic level. Two long-range spin chains and underlying quantum many-body system with spins have recently been uncovered.

- **Vertex-type.** In [MZ23a, MZ23b], Matushko and Zotov (MZ) constructed a fully anisotropic elliptic spin-Ruijsenaars model based on the Baxter–Belavin R -matrix [Bax72, Bel81]. The corresponding spin chain q -deforms Sechin and Zotov’s elliptic generalisation [SZ18] of the (antiperiodic) Fukui–Kawakami chain [FK96], cf. [KL25].
- **Face-type.** In [KL24], we defined a partially (an)isotropic, i.e. xxz-like, elliptic spin-Ruijsenaars system based on Felder’s dynamical R -matrix [Fel95b]. The associated spin chain q -deforms the Inozemtsev chain and moreover is an elliptic generalisation of the q -deformed Haldane–Shastry chain.

For a detailed analysis of the (almost entirely disjoint) landscapes in which these two families of integrable long-range spin chains live, see [KL25], summarised in Figures 2–3 therein.

In [MZ23a], the formalism for freezing from the trigonometric case [TH95, Ugl95, LPS22] was used to obtain a spin chain from their elliptic (vertex-type) spin-Ruijsenaars system. This involves expanding around a classical equilibrium configuration of the (elliptic) scalar Ruijsenaars system for which all momenta vanish, $p_i^* = 0$, where we use ‘ $\star$ ’ for a classical equilibrium. This expansion coincides with a strong-coupling expansion of the shift operators (multiplicative momenta), $\Gamma_i = e^{\epsilon \hat{p}_i} = 1 + \epsilon \hat{p}_i + O(\epsilon^2)$, in a parameter $\epsilon \propto 1/g$. However, compared to the trigonometric case, a new feature at the elliptic level is the existence of a large number of classical equilibria, almost all of which have non-vanishing momenta, as we shall see. It is precisely such equilibria that give rise to spin chains with a well-defined (i.e. convergent) short-range limit [KL24, KL25]. This requires a modification of the freezing procedure from [MZ23a] in order to account for the contribution from the nontrivial classical limit $\Gamma_i \rightarrow e^{\epsilon p_i^*}$. Surprisingly, the resulting ‘MZ’ chain [KL25] turns out to differ from the original MZ chain [MZ23a] simply by

a shift over a multiple of the identity [KL25]. In contrast, in the (face-type) dynamical case of [KL24] the two ways of freezing produce q -deformed Inozemtsev chains that differ more drastically—do not even commute—with only the version considered in [KL24, KL25] admitting a short-range limit. The upshot is that both the MZ' chain and the q -deformed Inozemtsev chain enable an analytic comparison between long- and short-range regimes via interpolation. However, it remains to be proven that these interpolating spin chains are indeed integrable. In the vertex case, this provides a direct and more general alternative to the combination of the proof of integrability for the MZ chain [MZ23a] and the simple difference with the MZ' chain established in [KL25]. In the face setting, it requires a separate proof. In this paper we provide a technical but crucial step to narrow this gap. Besides proving integrability, we expect this to be very useful for the study of the spectrum. Indeed, for the (q -deformed and ordinary) Haldane–Shastry chain, the eigenvalues, eigenvectors, and (nonabelian) symmetries are understood via the connection to quantum many-body systems provided by freezing.

Our main aim is to develop a framework for freezing elliptic spin-Ruijsenaars systems around *any* equilibrium of their spinless classical limit.

Outline. In §2 we review these systems at the quantum level in a framework allowing for a uniform treatment of the face and vertex versions. We *assume* the spin-QMBS is integrable (in the sense that it comes with as many commuting difference operators as there are particles); in the vertex case this was proven in [MZ23a], while in the face case the proof is forthcoming.

We study the classical level of the scalar model and its equilibria in §3, exhibiting an $\mathrm{SL}(2, \mathbb{Z})$ -action that connects equilibria associated to the same (elliptic) lattice.

In §4 we employ deformation quantisation to freeze any of the QMBS with spins at any classical equilibrium configuration and *prove* that the resulting spin chain is integrable. This is closely related to the settings of [MV24, LRS24]. The result is an $\mathrm{SL}(2, \mathbb{Z})$ -family of integrable long-range spin chains. We conclude in §5.

The appendix consists of two parts. §A contains all necessary definitions and properties of elliptic functions and R -matrices. §B has more details about the deformed spin permutations from which the spin-Ruijsenaars operators are built.

2. ELLIPTIC QUANTUM SPIN-RUIJSENAARS SYSTEMS

The (quantum, elliptic) Ruijsenaars system, see [Rui04] for an overview, describes N interacting particles moving on a circle with coordinates x_j . We will simply denote the space of states, which consists of suitable functions of $\mathbf{x} = (x_1, \dots, x_N)$, by $\mathrm{Fun}(\mathbf{x})$.¹ Fix an arbitrary elliptic parameter τ with $\mathrm{Im} \tau > 0$. We take the (odd) Jacobi theta function to be defined as

$$(2.1) \quad \theta(x | \tau) := \frac{\sin(\pi x)}{\pi} \prod_{n=1}^{\infty} \frac{\sin(\pi(n\tau + x)) \sin(\pi(n\tau - x))}{\sin^2(\pi n \tau)}.$$

More details on the elliptic functions that we use, which are all defined in terms of (2.1), can be found in §A. Given $\epsilon \in \mathbb{C}$, consider the shift operators $\Gamma_i := e^{-i\hbar\epsilon\partial_{x_i}}$, acting on $\mathrm{Fun}(\mathbf{x})$ as

$$(2.2) \quad (\Gamma_i f)(\mathbf{x}) = f(x_1, \dots, x_i - i\hbar\epsilon, \dots, x_N).$$

We suppress the dependence of Γ_i on $\hbar$ and ϵ . Then, up to a conjugation (‘gauge transformation’) [Has97], the Ruijsenaars system is defined through the N difference operators [Rui87]

$$(2.3) \quad D_n(\mathbf{x}; \hbar, \eta, \epsilon | \tau) := \sum_{\substack{I \subset \{1, \dots, N\} \\ |I|=n}} A_I(\mathbf{x}; \eta | \tau) \Gamma_I, \quad \Gamma_I := \prod_{i \in I} \Gamma_i, \quad 1 \leq n \leq N.$$

¹ We will be interested in formal and algebraic structures rather than (functional) analysis. For simplicity, we take $\mathrm{Fun}(\mathbf{x})$ to consist of meromorphic functions on which the action of finite products of Γ_i is well defined. One may wish to impose appropriate quasiperiodicity properties, cf. equation (26) of [Has94].

Here the sum is over n -element subsets of $\{1, \dots, N\}$ and the coefficients are given by

$$(2.4) \quad A_I(\mathbf{x}; \eta | \tau) := \prod_{i \in I \ncong j} \frac{\theta(x_i - x_j + \eta | \tau)}{\theta(x_i - x_j | \tau)},$$

where the product runs over $i \in I$ and $j \in \{1, \dots, N\} \setminus I$, and $\eta \in \mathbb{C}$ is a parameter. When there is no cause for confusion we will often suppress the range of the sum or the dependence of the coefficients on either or both parameters η and τ . Thus, (2.3) acquires the compact form $D_n = \sum_I A_I(\mathbf{x}) \Gamma_I$.

The Ruijsenaars system is (quantum) integrable in the sense that the difference operators (2.3) commute,

$$(2.5) \quad [D_n, D_m] = 0.$$

We are interested in *matrix-valued* generalisations of (2.3) for which this commutativity persists.

To this end, we generalise the state space to the space $\text{Fun}(\mathbf{x}) \otimes V^{\otimes N}$ of vector-valued functions, where each particle carries a ‘spin’ that lives in a complex vector space $V \cong \mathbb{C}^r$ for $r \in \mathbb{Z}_{\geq 1}$. The scalar case $r = 1$ gives back the spinless Ruijsenaars system (2.3). The *integrable* matrix-valued difference operators that we will consider are built from R -matrices. In view of the coefficients (2.4) it is natural to consider *elliptic* R -matrices, which come in two well-known variants: the Baxter–Belavin (‘vertex-type’) R -matrix [Bax72, Bel81] and Felder’s dynamical (‘face-type’) R -matrix [Bax73, Fel95b]. The resulting matrix-valued generalisations of (2.3) are the spin-Ruijsenaars systems of Matushko and Zotov [MZ23a, MZ24] and our dynamical spin-Ruijsenaars systems [KL24], respectively. For $r > 1$ these two models are different, cf. §5.2 in [KL25], yet they look very similar. A uniform description goes as follows.

2.1. Deformed spin permutations. Consider a ‘generalised R -matrix’ in the sense of [Che92]. That is, suppose we have a family of linear operators $P_{i,i+1}(u) = P_{i,i+1}(u; \eta | \tau)$ on $V^{\otimes N}$ obeying the unitarity condition

$$(2.6) \quad P_{i,i+1}(u) P_{i,i+1}(-u) = \text{id},$$

the (‘braided’) Yang–Baxter equation²

$$(2.7) \quad P_{i,i+1}(u) P_{i+1,i+2}(u+v) P_{i,i+1}(v) = P_{i+1,i+2}(v) P_{i,i+1}(u+v) P_{i+1,i+2}(u),$$

and the commutativity

$$(2.8) \quad [P_{i,i+1}(u), P_{j,j+1}(v)] = 0, \quad |i - j| > 1.$$

We are particularly interested in the following two examples. Let $\mathbb{1}$ denote the identity on V , and P the flip on $V \otimes V$.

- **Vertex-type.** Let $R(u) = R(u; \eta | \tau)$ be the Baxter–Belavin R -matrix, which is Baxter’s eight-vertex R -matrix if $r = 2$, see §A.2.1. Set $\check{R}(u) = P R(u)$. Then (2.6)–(2.8) hold for

$$(2.9) \quad P_{i,i+1}^V(u) = \mathbb{1}^{\otimes(i-1)} \otimes \check{R}(u; \eta | \tau) \otimes \mathbb{1}^{\otimes(N-i-1)}.$$

- **Face-type.** Let $R(u, \vec{a}) = R(u, \vec{a}; \eta | \tau)$ be Felder’s dynamical R -matrix of type $\mathfrak{gl}_r$, involving ‘dynamical’ parameters $\vec{a} = (a_1, \dots, a_r)$, see §A.2.2. It obeys the *dynamical* Yang–Baxter equation, in which the dynamical parameters $\vec{a}$ are shifted depending on the weight of the factors of V to the left of the R -matrix. Namely, write $|\vec{\mu}\rangle\langle\vec{\mu}|$ for the projection onto the weight- $\vec{\mu}$ subspace of $V^{\otimes(i-1)}$. Again putting $\check{R}(u, \vec{a}) = P R(u, \vec{a})$, we now take

$$(2.10) \quad P_{i,i+1}^F(u) = \sum_{\vec{\mu}} |\vec{\mu}\rangle\langle\vec{\mu}| \otimes \check{R}(u, \vec{a} - \eta \vec{\mu}; \eta | \tau) \otimes \mathbb{1}^{\otimes(N-i-1)}.$$

Since $\sum_{\vec{\mu}} |\vec{\mu}\rangle\langle\vec{\mu}| = \mathbb{1}^{\otimes(i-1)}$ is (a resolution of) the identity, (2.10) acts nontrivially only on the i th and $i + 1$ st factors of $V^{\otimes N}$. The shifts of $\vec{a}$ ensure that (2.7) is equivalent to the dynamical Yang–Baxter equation. The operators (2.10) also satisfy (2.6)–(2.8).

² The braided setting simplifies keeping track of the shifts of the dynamical parameters in the face-type setting.

Since both of these examples moreover obey the condition

$$(2.11) \quad P_{i,i+1}(u)|_{\eta=0} = P_{i,i+1} := \mathbb{1}^{\otimes(i-1)} \otimes P \otimes \mathbb{1}^{\otimes(N-i-1)},$$

we think of $P_{i,i+1}(u)$ as a $(q-)$ deformed nearest-neighbour spin *Permutation* operator.

We will use the standard graphical notation: each copy of the vector space V (containing a spin) is drawn as a vertical line, which carries an ‘inhomogeneity parameter’. The ‘deformed spin permutation’ $P_{i,i+1}(u)$ is a crossing of the i and $i+1$ st lines, which each carry along their inhomogeneities,

$$(2.12) \quad P_{i,i+1}(u) = \bar{a} \uparrow \cdots \uparrow \begin{array}{c} x' \quad x \\ \diagup \quad \diagdown \\ \diagdown \quad \diagup \\ x \quad x' \end{array} \uparrow \cdots \uparrow, \quad u = x - x'.$$

The only difference between the vertex- and face-type examples for $P(u)$ is that, in the latter case, the left-most face is decorated with the dynamical parameters $\bar{a}$ (indicated in gray), determining the dynamical parameters on all other faces, see §A.2.2. Then (2.6) with $u = x - x'$ becomes

$$(2.13) \quad \bar{a} \uparrow \cdots \uparrow \begin{array}{c} x \quad x' \\ \diagup \quad \diagdown \\ \diagdown \quad \diagup \\ x \quad x' \end{array} \uparrow \cdots \uparrow = \bar{a} \uparrow \cdots \uparrow \begin{array}{c} x \quad x' \\ \uparrow \quad \uparrow \\ x \quad x' \end{array} \uparrow \cdots \uparrow,$$

while (2.7) with in addition $v = x' - x''$ is

$$(2.14) \quad \bar{a} \uparrow \cdots \uparrow \begin{array}{c} x'' \quad x' \quad x \\ \diagup \quad \diagdown \quad \diagup \\ \diagdown \quad \diagup \quad \diagdown \\ x \quad x' \quad x'' \end{array} \uparrow \cdots \uparrow = \bar{a} \uparrow \cdots \uparrow \begin{array}{c} x'' \quad x' \quad x \\ \diagup \quad \diagdown \quad \diagup \\ \diagdown \quad \diagup \quad \diagdown \\ x \quad x' \quad x'' \end{array} \uparrow \cdots \uparrow.$$

Note that, while the inhomogeneities are carried around by the lines, (the subscripts labelling) the vector spaces do not move, since we work with $\check{R}(x) = P R(x)$. In the following, each diagram starts out (at the bottom) with inhomogeneity parameters given by the particle coordinates $x_1, \dots, x_N$.

We can now define an operator $P_w(\mathbf{x})$ for any permutation $w \in S_N$, cf. [Che92]. We start from the identity $e \in S_N$, for which

$$(2.15) \quad P_e(\mathbf{x}) = \text{id} = \bar{a} \uparrow \begin{array}{c} x_1 \quad x_2 \quad \cdots \quad x_N \\ \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \\ x_1 \quad x_2 \quad \cdots \quad x_N \end{array}.$$

All other operators are constructed from this by recursion via the *cocycle condition*

$$(2.16) \quad P_{w(i,i+1)}(\mathbf{x}) = P_w(x_1, \dots, x_{i+1}, x_i, \dots, x_N) P_{i,i+1}(x_i - x_{i+1}),$$

where the swap $x_i \leftrightarrow x_{i+1}$ for P_w takes into account how the parameters move around. The result is well defined thanks to (2.6)–(2.8). Note that $P_w(\mathbf{x})$ does not always actually depend on all parameters $x_1, \dots, x_N$, as (2.15) already illustrates.

Next, the permutations w that appear in the n th spin-Ruijsenaars operator can be concisely defined as follows. Given an n -element subset $I = \{i_1 < \dots < i_n\} \subseteq \{1, \dots, N\}$, consider the (Grassmannian) permutation $w_I \in S_N$ that sends $k \mapsto i_k$ for all $1 \leq k \leq n$ while permuting neither any of $\{1, \dots, n\}$ amongst each other, nor any of $\{n+1, \dots, N\}$. From it, we define

$$(2.17) \quad P_I(\mathbf{x}) := P_{w_I^{-1}}(\mathbf{x}), \quad P_{-I}(\mathbf{x}) := P_{\{1, \dots, N\} \setminus I}(\mathbf{x}).$$

For example, at $n = 1$ the cycle $w_{\{i\}} = (i \ i - 1 \ \dots \ 1)$ gives

$$(2.18) \quad P_{\{i\}}(\mathbf{x}) = P_{(1 \ \dots \ i-1 \ i)}(\mathbf{x}) = P_{12}(x_1 - x_i) \cdots P_{i-1,i}(x_{i-1} - x_i) = \bar{a} \begin{array}{c} x_i \quad x_1 \quad \dots \quad x_{i-1} \quad x_N \\ \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \\ \text{diagram of crossings} \\ \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \\ x_1 \quad \dots \quad x_{i-1} \quad x_i \quad x_N \end{array}.$$

As n increases the $P_I(\mathbf{x})$ become more complicated, until $n = N/2$, when they simplify again, and it is more convenient to switch to the $P_{-I}(\mathbf{x})$. Since $w_{\{1, \dots, N\}} = e$, the first nontrivial example is

$$(2.19) \quad P_{-\{i\}}(\mathbf{x}) = P_{(N \ N-1 \ \dots \ i)}(\mathbf{x}) = P_{N-1,N}(x_i - x_N) \cdots P_{i,i+1}(x_i - x_{i+1}) = \bar{a} \begin{array}{c} x_1 \quad x_{i+1} \quad \dots \quad x_N \quad x_i \\ \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \\ \text{diagram of crossings} \\ \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \\ x_1 \quad x_i \quad x_{i+1} \quad \dots \quad x_N \end{array}.$$

For more about these deformed spin permutations, including further examples, see §B.

2.2. Matrix-valued Ruijsenaars operators. In terms of the deformed spin permutations, the spin-generalisations of the scalar Ruijsenaars operators (2.3) read

$$(2.20) \quad \tilde{D}_n(\mathbf{x}; \hbar, \eta, \epsilon, \bar{a} | \tau) = \sum_{|I|=n} A_I(\mathbf{x}) P_I(\mathbf{x})^{-1} \Gamma_I P_I(\mathbf{x}).$$

They depend on the parameters from the scalar case, along with any further parameters from the R -matrix (e.g. $\bar{a}$ in the vertex-type case); again, we will often suppress this from our notation. The first spin-Ruijsenaars operator thus takes the form

$$(2.21) \quad \begin{aligned} \tilde{D}_1 &= \sum_{i=1}^N A_i(\mathbf{x}) P_{(1 \ \dots \ i)}(\mathbf{x})^{-1} \Gamma_i P_{(1 \ \dots \ i)}(\mathbf{x}) \\ &= \sum_{i=1}^N A_i(\mathbf{x}) \times \begin{array}{c} x_1 \quad \dots \quad x_i \quad \dots \quad x_N \\ \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \\ \text{diagram of crossings} \\ \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \\ x_1 \quad \dots \quad x_i^- \quad \dots \quad x_N \end{array} \quad \begin{array}{c} x_i \\ \uparrow \\ \epsilon \bullet = \Gamma_i, \\ \downarrow \\ x_i^- \end{array} \quad x_i^- \equiv x_i - i \hbar \epsilon \\ &= \sum_{i=1}^N A_i(\mathbf{x}) P_{(1 \ \dots \ i)}(\mathbf{x})^{-1} P_{(1 \ \dots \ i)}(x_1, \dots, x_i^-, \dots, x_N) \Gamma_i, \end{aligned}$$

where in the last line we pushed the difference operator to the right. Higher spin-Ruijsenaars operators can be depicted and explicitly given similarly, see e.g. (4.45) below for $n = 2$.

Like for the spin permutations $P_I(\mathbf{x})$, there is a sort of symmetry between $\tilde{D}_{N-n}$ and $\tilde{D}_n$, as follows. The last difference operator $\tilde{D}_N = \Gamma_1 \cdots \Gamma_N = D_N$ is just the total coordinate-shift operator, and acts as the identity on spins. Since all $\tilde{D}_n$ only depend on *differences* of coordinates, they commute with $\tilde{D}_N$ (for any choice of R -matrix). Using that $\tilde{D}_N$ is clearly invertible, it will sometimes be convenient to simplify operators ‘beyond the equator’, i.e. with $n > N/2$, by defining

$$(2.22) \quad \begin{aligned} \tilde{D}_{-n} &:= D_N^{-1} \tilde{D}_{N-n} \\ &= \sum_{|I|=n} A_{-I}(\mathbf{x}) P_{-I}(\mathbf{x})^{-1} \Gamma_{-I} P_{-I}(\mathbf{x}), \end{aligned}$$

where $A_{-I}(\mathbf{x}) := A_I(-\mathbf{x}) = A_I(\mathbf{x})|_{\eta \mapsto -\eta}$ and $\Gamma_{-I} := \Gamma_I^{-1} = \Gamma_I|_{\epsilon \mapsto -\epsilon}$. The equality in the second line of (2.22) uses unitarity (2.6) and the Yang–Baxter equation (2.7). For example,

$$\begin{aligned}
(2.23) \quad \tilde{D}_{-1} &= \sum_{i=1}^N A_{-i}(\mathbf{x}) P_{(N \ N-1 \ \dots \ i)}(\mathbf{x})^{-1} \Gamma_i^{-1} P_{(N \ N-1 \ \dots \ i)}(\mathbf{x}) \\
&= \sum_{i=1}^N A_{-i}(\mathbf{x}) \times \begin{array}{c} x_1 \quad \dots \quad x_i \quad \dots \quad x_N \\ \uparrow \quad \quad \uparrow \quad \quad \uparrow \quad \quad \uparrow \quad \quad \uparrow \\ \vdots \quad \quad \vdots \quad \quad \vdots \quad \quad \vdots \quad \quad \vdots \\ x_1 \quad \dots \quad x_i^+ \quad \dots \quad x_N \end{array} \quad \begin{array}{c} \text{Diagram showing a crossing of lines with a dot and label } -\epsilon \\ \text{Diagram showing a vertical line with a dot and label } -\epsilon \end{array} \\
&= \sum_{i=1}^N A_{-i}(\mathbf{x}) P_{(N \ N-1 \ \dots \ i)}(\mathbf{x})^{-1} P_{(N \ N-1 \ \dots \ i)}(x_1, \dots, x_i^+, \dots, x_N) \Gamma_i^{-1}.
\end{aligned}$$

For certain choices of R -matrices, the spin-Ruijsenaars operators all commute with each other,

$$(2.24) \quad [\tilde{D}_n, \tilde{D}_m] = 0,$$

for all n, m in $\{1, \dots, N\}$ (or $\{1 - N, \dots, -1\}$). In the case of elliptic coefficients A_I given by (2.4), the R -matrices need to be elliptic too. In the (vertex) case with (2.9) the Baxter–Belavin R -matrix, (2.24) was proven by Matushko and Zotov [MZ23a]. For the (face) case with (2.10) Felder’s dynamical R -matrix, we announced the analogous result in [KL24]; our proof goes well beyond this paper, and will appear elsewhere.

3. CLASSICAL LEVEL: ELLIPTIC RUIJSENAARS–SCHNEIDER SYSTEM

Now we turn to the classical level. The classical Ruijsenaars–Schneider system depends on the parameters $(\eta, \epsilon | \tau) \in \mathbb{C}^2 \times \mathbb{H}$, with $\mathbb{H} := \{z \in \mathbb{C} : \text{Im } z > 0\}$ the upper half plane.

Consider the classical phase space $M = T^*\mathbb{R}^N \cong \mathbb{R}^{2N}$ with coordinates x_i and conjugate momenta p_j obeying canonical Poisson brackets

$$(3.1a) \quad \{x_i, x_j\} = \{p_i, p_j\} = 0, \quad \{x_i, p_j\} = \delta_{ij}.$$

The multiplicative momenta $\gamma_i := e^{\epsilon p_i}$ provide coordinates satisfying

$$(3.1b) \quad \{x_i, x_j\} = \{\gamma_i, \gamma_j\} = 0, \quad \{x_i, \gamma_j\} = \epsilon \delta_{ij} \gamma_j.$$

We will work in the setting of algebraically integrable systems, with complexified phase space $M_{\mathbb{C}} = T^*\mathbb{C}^N \cong \mathbb{C}^{2N}$. The associated Poisson algebra of suitable¹ (p. 3) functions on $M_{\mathbb{C}}$ contains

$$(3.2) \quad \mathcal{A}_0 := \text{Fun}(\mathbf{x})[\gamma_1^{\pm 1}, \dots, \gamma_N^{\pm 1}]$$

as a Poisson subalgebra. The *Ruijsenaars–Schneider* (RS) system is defined by the functions

$$(3.3) \quad D_n^{\text{cl}}(\mathbf{x}, \mathbf{p}; \eta | \tau) := \sum_{\substack{I \subset \{1, \dots, N\} \\ \#I = n}} A_I(\mathbf{x}; \eta | \tau) \gamma_I \in \mathcal{A}_0, \quad 1 \leq n \leq N, \quad \gamma_I := \prod_{i \in I} \gamma_i,$$

with the same coefficients (2.4). This (spinless, classical) many-body system is Liouville integrable [RS86]: the N functions (3.3) Poisson commute,

$$(3.4) \quad \{D_n^{\text{cl}}, D_m^{\text{cl}}\} = 0.$$

For the physical interpretation, first observe that the coefficients obey the symmetry properties $A_{I^c}(\mathbf{x}) = A_{-I}(\mathbf{x})$ where $I^c := \{1, \dots, N\} \setminus I$ denotes the complement of I . Since $D_N^{\text{cl}} = \gamma_1 \cdots \gamma_N = \exp(\epsilon \sum_j p_j)$, additional functions resembling (3.3) arise by setting

$$(3.5) \quad D_{-n}^{\text{cl}} := \frac{D_{N-n}^{\text{cl}}}{D_N^{\text{cl}}} = \sum_{\substack{I \subset \{1, \dots, N\} \\ \#I=n}} A_I(\mathbf{x}; -\eta) \gamma_I^{-1} = D_n^{\text{cl}} \Big|_{\substack{\eta \mapsto -\eta \\ \epsilon \mapsto -\epsilon}} \in \mathcal{A}_0, \quad 1 \leq n \leq N,$$

in complete analogy with (2.22). For the reader who likes physical units, let m_0 denote the rest mass, and c the speed of light. Now form the combinations

$$(3.6) \quad P^{\text{cl}} := m_0 c \frac{D_1^{\text{cl}} - D_{-1}^{\text{cl}}}{2}, \quad H^{\text{cl}} := m_0 c^2 \frac{D_1^{\text{cl}} + D_{-1}^{\text{cl}}}{2}.$$

For a single particle we recognise

$$(3.7) \quad N = 1 : \quad \begin{aligned} P^{\text{cl}} &= m_0 c \sinh(\epsilon p), \\ H^{\text{cl}} &= m_0 c^2 \cosh(\epsilon p) = \sqrt{(m_0 c^2)^2 + (c P^{\text{cl}})^2}, \end{aligned} \quad \epsilon = \frac{1}{m_0 c},$$

as the momentum and energy of a relativistic particle with p/m_0 playing the role of rapidity. The functions (3.6) are N -particle generalisations of (3.7) belonging to the family (3.3) that is Liouville integrable.

3.1. Modularity. We will be interested in families of hamiltonians associated to a *fixed* (quasi-) period lattice $\Lambda_\tau := \mathbb{Z} + \tau \mathbb{Z} \subset \mathbb{C}$, with modular parameter $\tau \in \mathbb{H}$. Such a lattice defines an elliptic curve $\mathbb{C}/\Lambda_\tau$, and homothetic lattices yield isomorphic curves. It is well known that all homothetic lattices are related by an action of the modular group

$$(3.8) \quad \text{PSL}(2, \mathbb{Z}) = \langle S, T \mid S^2 = 1 = (ST)^3 \rangle,$$

whose action on $\mathbb{H}$ is generated by the signed inversion $S: \tau \mapsto -1/\tau$ and the translation $T: \tau \mapsto \tau + 1$, see e.g. [Sil94]. To keep the lattice *invariant*, this action has to be combined with a rescaling of the ambient copy of $\mathbb{C} \supset \Lambda_\tau$, see Fig. 1. Indeed, $\Lambda_\tau = c \Lambda_{\tau'}$ for some $\tau' \in \mathbb{H}$ and $c \in \mathbb{C}^\times$ precisely when $\tau = B \cdot \tau'$ for some $B \in \text{PSL}(2, \mathbb{Z})$. Note that, given z in this ambient copy of $\mathbb{C}$, applying the S -transformation twice gives

$$(3.9) \quad (z \mid \tau) \mapsto (-z/\tau \mid -1/\tau) = (z' \mid \tau') \mapsto (-z'/\tau' \mid -1/\tau') = (-z \mid \tau),$$

where the second application uses the updated modular parameter τ' . Due to the sign on the right-hand side of (3.9), we are led to an action of the double cover

$$(3.10) \quad \text{SL}(2, \mathbb{Z}) = \langle S, T \mid S^4 = 1 = (ST)^6 \rangle$$

of the modular group $\text{PSL}(2, \mathbb{Z}) = \text{SL}(2, \mathbb{Z})/\langle \pm 1 \rangle$.³ See Fig. 1.

It is not directly obvious how the Ruijsenaars–Schneider functions (3.3) with modular parameter $-1/\tau$ are related to their cousins with parameter τ . We will now construct a variant of the modular transformations that allows for a simple relation between the transformed and original Ruijsenaars–Schneider functions.

In the setting of dynamical systems, the coordinates x_j live in the ambient $\mathbb{C}$, so we simultaneously rescale $x_i \mapsto c x_i$ with $c \in \mathbb{C}^\times$. To preserve the canonical Poisson brackets (3.1a) we also rescale all $p_j \mapsto p_j/c$, while the Poisson brackets (3.1b) require rescaling the parameter ϵ as $\epsilon \mapsto c \epsilon$.⁴ It is then natural to rescale the remaining parameter $\eta \mapsto c \eta$ as well, in order to preserve the form of the coefficients (2.4) appearing in (3.3). Altogether, we are thus led to an action of $\text{SL}(2, \mathbb{Z})$ on $M_{\mathbb{C}} \times \mathbb{C}^2 \times \mathbb{H}$ given by

$$(3.11) \quad (\mathbf{x}, \mathbf{p}; \eta, \epsilon \mid \tau) \mapsto (c \mathbf{x}, \mathbf{p}/c; c \eta, c \epsilon \mid B \cdot \tau), \quad B \in \text{SL}(2, \mathbb{Z}), \quad c \in \mathbb{C}^\times,$$

which restricts to a symplectomorphism of the complexified phase space $M_{\mathbb{C}} = T^* \mathbb{C}^N$. Explicitly, this action is generated by

$$(3.12) \quad \begin{aligned} S &: (\mathbf{x}, \mathbf{p}; \eta, \epsilon \mid \tau) \mapsto (-\mathbf{x}/\tau, -\tau \mathbf{p}; -\eta/\tau, -\epsilon/\tau \mid -1/\tau), \\ T &: (\mathbf{x}, \mathbf{p}; \eta, \epsilon \mid \tau) \mapsto (\mathbf{x}, \mathbf{p}; \eta, \epsilon \mid \tau + 1). \end{aligned}$$

³ One can also see that S now has order 4 by keeping track of both lattice vectors (periods). To preserve the orientation, the order of the two vectors is swapped under the action $S: \Lambda_{1,\tau} \mapsto -\tau \Lambda_{1,-1/\tau} = \Lambda_{-\tau,1}$ (cf. Fig. 1). Applying S again thus gives $\Lambda_{-\tau,1} \mapsto \Lambda_{-1,-\tau} = -\Lambda_{1,\tau}$, so $S^2 = -1$.

⁴ Note that this rescaling preserves the multiplicative momenta $\gamma_j = e^{\epsilon p_j}$ at the classical level, and also the operators (2.2) at the quantum level.

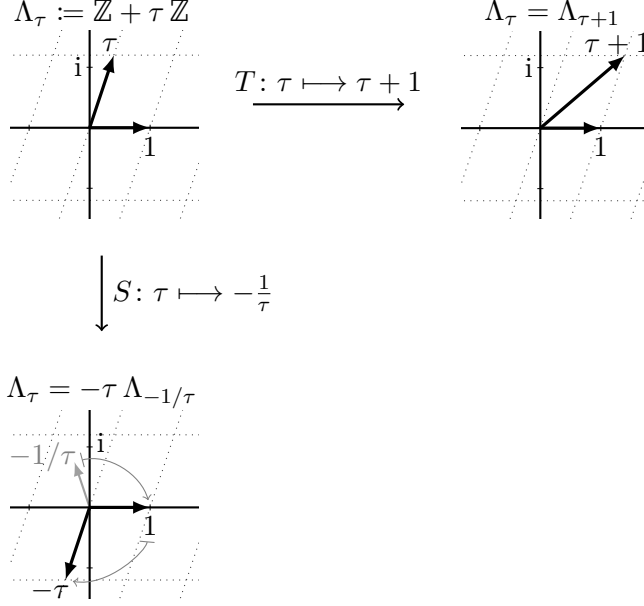


FIGURE 1. The generator T of $\mathrm{SL}(2, \mathbb{Z})$ simply shifts the modular parameter of the lattice $\Lambda_\tau \subset \mathbb{C}$ as $\tau \mapsto \tau + 1$. The generator S acts by a signed inversion, $\tau \mapsto -1/\tau$, which requires a simultaneous coordinate rescaling $x \mapsto -\tau x$ in order to fix the lattice, as indicated.

On a theta function $\theta(x|\tau)$ where x is any linear combination of the x_i and p_j , these two generators yield nothing but the Jacobi imaginary transformation and a simple shift of τ :

$$(3.13) \quad \theta(-x/\tau | -1/\tau) = i(-i\tau)^{1/2} e^{i\pi x^2/\tau} \theta(x|\tau), \quad \theta(x|\tau+1) = e^{i\pi/4} \theta(x|\tau).$$

Because of the prefactors in (3.13) it is not immediately obvious what the effect is of the modular action on the dynamics of the Ruijsenaars–Schneider system. We push forward the $\mathrm{SL}(2, \mathbb{Z})$ -action on $M_{\mathbb{C}} \times \mathbb{C}^2 \times \mathbb{H}$ to functions $f: M_{\mathbb{C}} \times \mathbb{C}^2 \times \mathbb{H} \rightarrow \mathbb{C}$, and consider the D_n^{cl} . The action of T then results in

$$(3.14) \quad T \cdot D_n^{\mathrm{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau) = D_n^{\mathrm{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau + 1) = D_n^{\mathrm{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau),$$

as follows from (3.13) and the fact that the coefficients A_I are homogeneous of degree 0 in theta functions. Since the Poisson brackets are preserved under this action, so are the dynamics.

The effect of the S -transformation is more complicated. Observe that the Jacobi imaginary transformation implies

$$(3.15) \quad \frac{\theta(-(x+\eta)/\tau | -1/\tau)}{\theta(-x/\tau | -1/\tau)} = e^{i\pi(\eta^2+2\eta x)/\tau} \frac{\theta(x+\eta | \tau)}{\theta(x | \tau)}.$$

Thus

$$(3.16) \quad \begin{aligned} S \cdot D_n^{\mathrm{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau) &= D_n^{\mathrm{cl}}(-\mathbf{x}/\tau, -\tau \mathbf{p}; -\eta/\tau, -\epsilon/\tau | -1/\tau) \\ &= \sum_{|I|=n} A_I(-\mathbf{x}/\tau; -\eta/\tau | -1/\tau) \gamma_I \\ &= \sum_{|I|=n} A_I(\mathbf{x}; \eta | \tau) \exp\left(\frac{i\pi}{\tau} \left(n(N-n)\eta^2 + 2\eta \sum_{j \in I \neq k} (x_j - x_k)\right)\right) \gamma_I \\ &= e^{i\pi n(N-n)\eta^2/\tau} \sum_{|I|=n} A_I(\mathbf{x}; \eta | \tau) \exp\left(\frac{2\pi i \eta}{\tau} \left(N \sum_{j \in I} x_j - n|\mathbf{x}|\right) + \epsilon \sum_{j \in I} p_j\right), \end{aligned}$$

where $|\mathbf{x}| := \sum_{i=1}^N x_i$. The exponential factor in the sum can be made independent of I by a suitable shift of the momenta $\mathbf{p}$, namely

$$(3.17) \quad p_j \mapsto p_j + \frac{2\pi i \eta}{\epsilon \tau} \sum_{k=1}^N (x_k - x_j) = p_j + \frac{2\pi i \eta}{\epsilon \tau} (|\mathbf{x}| - Nx_j).$$

This shift does not only preserve the value $\sum_j p_j^*$ of the total momentum and thus the value of $D_N^{\text{cl}*} = \gamma_1^* \cdots \gamma_N^*$, but also the symplectic structure. Indeed, one readily verifies that $\{p_i, p_j\} = 0$ is respected by (3.17).

We therefore modify the action (3.12) to incorporate the momentum shift (3.17):

$$(3.18) \quad \begin{aligned} S: (\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau) &\mapsto \left(-\frac{\mathbf{x}}{\tau}, -\tau \mathbf{p} - \frac{2\pi i \eta}{\epsilon} \sum_{j=1}^N (|\mathbf{x}| - Nx_j) \mathbf{e}_j; -\frac{\eta}{\tau}, -\frac{\epsilon}{\tau} \middle| -\frac{1}{\tau} \right), \\ T: (\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau) &\mapsto (\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau + 1), \end{aligned}$$

with $\mathbf{e}_j$ the unit vector with a 1 in the j th entry. A direct computation shows that this still defines an action of $\text{SL}(2, \mathbb{Z})$. Indeed, the shifts (3.17) cancelling after every second S -transformation to leave just an overall minus sign for the x_j as well as η ; since the theta function is odd, these signs cancel in $A_I(\mathbf{x})$. Hence, on the Ruijsenaars functions D_n^{cl} , and more generally on all functions invariant under $(\mathbf{x}; \eta) \mapsto (-\mathbf{x}; -\eta)$, we get an action of $\text{PSL}(2, \mathbb{Z})$ obtained by quotienting out $S^2 = -1$. Setting $c_n(\eta) := e^{i\pi n(N-n)\eta^2/\tau}$ allows us to write

$$(3.19) \quad S \cdot D_n^{\text{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau) = c_n(\eta) D_n^{\text{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau).$$

3.2. Equilibrium configurations. Due to the Poisson commutativity (3.4), each of the integrals of motion (3.3) generates a time flow $\partial/\partial t_n = \{\cdot, D_n^{\text{cl}}\}$ under which all other D_m^{cl} are preserved. The corresponding velocities and jerks (jolts) are

$$(3.20a) \quad \frac{\partial x_i}{\partial t_n} = \{x_i, D_n^{\text{cl}}\} = + \frac{\partial D_n^{\text{cl}}}{\partial p_i} = \epsilon \sum_{I: I \ni i} A_I(\mathbf{x}) \gamma_I$$

and

$$(3.20b) \quad \frac{\partial p_j}{\partial t_n} = \{p_j, D_n^{\text{cl}}\} = - \frac{\partial D_n^{\text{cl}}}{\partial x_j} = - \sum_I \partial_{x_j} A_I(\mathbf{x}) \gamma_I,$$

where the sums run over all n -element subsets $I \subset \{1, \dots, N\}$, for (3.20a) subject to $i \in I$. We are interested in *classical equilibrium configurations*: points $(\mathbf{x}^*, \mathbf{p}^*) \in M_{\mathbb{C}}$ at which the functions (3.20) are fixed to values

$$(3.21) \quad \frac{\partial x_i^*}{\partial t_n} = v_n^*, \quad \frac{\partial p_j^*}{\partial t_n} = 0, \quad 1 \leq n \leq N,$$

for constants $v_n^* \in \mathbb{C}$ depending on the point $(\mathbf{x}^*, \mathbf{p}^*)$ and the system's parameters η, ϵ, τ , but *not* on $1 \leq i \leq N$. In particular, by (3.20a), the partial sums

$$(3.22) \quad v_n^* = \frac{\partial x_i^*}{\partial t_n} = \epsilon \sum_{I: I \ni i} A_I(\mathbf{x}^*) \gamma_I^*, \quad \gamma_I^* := \prod_{i \in I} \gamma_i^*, \quad \gamma_i^* := e^{\epsilon p_i^*},$$

must be independent of i . For the time flow with $n = 1$ this requires all summands $\epsilon A_i(\mathbf{x}^*) \gamma_i^* = v_1^*$ to coincide. Classical equilibrium configurations are ‘frozen’ in the sense that they remain stationary in the linearly co-moving frame with (constant) velocity v_n^* . Let us write $M_{\mathbb{C}}^* \subset M_{\mathbb{C}}$ for the set of all such classical equilibrium configurations in the complexified phase space.

Given parameters $(\eta, \epsilon | \tau) \in \mathbb{C}^2 \times \mathbb{H}$, suppose we have an equilibrium configuration $(\mathbf{x}^*, \mathbf{p}^*)$ for $D_n^{\text{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau)$ for which the associated constant velocities obey the symmetry properties

$$(3.23) \quad v_{N-n}^*(\eta) = v_n^*(-\eta) = v_n^*(\eta).$$

In due course we will verify that this is indeed the case.

Then the dynamical system defined by $B \cdot D_n^{\text{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau)$ also has an equilibrium configuration. To show this, it suffices to do so for the two generators. Since the action of T changes neither the symplectic structure nor the hamiltonians, cf. (3.14), it obviously preserves equilibrium configurations. So we concentrate on S . Let us denote by $\mathbf{x}' := S \cdot \mathbf{x} = -\mathbf{x}/\tau$ and $\mathbf{p}' := S \cdot \mathbf{p} = -\tau \mathbf{p} - 2\pi i \eta \epsilon^{-1}(|\mathbf{x}| - Nx_j)$ the coordinates on $M_{\mathbb{C}}$ obtained by applying the action of S . Since $(\mathbf{x}, \mathbf{p}) \mapsto (\mathbf{x}', \mathbf{p}')$ is a canonical transformation, for any two functions $f, g: M_{\mathbb{C}} \rightarrow \mathbb{C}$ the Poisson bracket in the transformed coordinates $\mathbf{x}', \mathbf{p}'$ can be expressed in terms of that in terms of the original coordinates as

$$(3.24) \quad \{f(\mathbf{x}', \mathbf{p}'), g(\mathbf{x}', \mathbf{p}')\}' = \{f(\mathbf{x}'(\mathbf{x}, \mathbf{p}), \mathbf{p}'(\mathbf{x}, \mathbf{p})), g(\mathbf{x}'(\mathbf{x}, \mathbf{p}), \mathbf{p}'(\mathbf{x}, \mathbf{p}))\},$$

and likewise for functions on $M_{\mathbb{C}} \times \mathbb{C}^2 \times \mathbb{H}$. For the transformed velocities (3.20a) we compute

$$(3.25) \quad \begin{aligned} \frac{\partial x'_i}{\partial t_n} &= \{x'_i, D_n^{\text{cl}}(\mathbf{x}', \mathbf{p}'; \eta', \epsilon' | \tau')\}' \\ &= \{x'_i(\mathbf{x}), D_n^{\text{cl}}(\mathbf{x}'(\mathbf{x}), \mathbf{p}'(\mathbf{p}); \eta', \epsilon' | \tau')\} \quad \text{by (3.24)} \\ &= \frac{c_n(\eta)}{-1/\tau} \{x_i, D_n^{\text{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau)\} \quad \text{by definition of } x'_i \text{ and (3.19)} \\ &= \frac{c_n(\eta)}{-1/\tau} \frac{\partial D_n^{\text{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau)}{\partial p_i}. \end{aligned}$$

Evaluating the coordinates at the equilibrium $(\mathbf{x}^*, \mathbf{p}^*)$, we obtain new velocities $v'_n(\eta) = \frac{c_n(\eta)}{-1/\tau} v_n(\eta)$. Similarly, for the transformed jerks (3.20b) we calculate

$$(3.26) \quad \begin{aligned} \frac{\partial p'_i}{\partial t_n} &= \{p'_i, D_n^{\text{cl}}(\mathbf{x}', \mathbf{p}'; \eta', \epsilon' | \tau')\}' \\ &= \{p'_i(\mathbf{x}, \mathbf{p}), D_n^{\text{cl}}(\mathbf{x}'(\mathbf{x}, \mathbf{p}), \mathbf{p}'(\mathbf{x}, \mathbf{p}); \eta', \epsilon' | \tau')\} \\ &= -c_n(\eta) \left\{ \tau p_i + \frac{2\pi i \eta}{\epsilon} (|\mathbf{x}| - Nx_i), D_n^{\text{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau) \right\} \\ &= -c_n(\eta) \left(\frac{\partial D_n^{\text{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau)}{\partial x_i} + \frac{2\pi i \eta}{\epsilon} \sum_{j=1}^N (1 - \delta_{ji} N) \times -\frac{\partial D_n^{\text{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau)}{\partial p_i} \right). \end{aligned}$$

At equilibrium this gives

$$(3.27) \quad \left. \frac{\partial p'_i}{\partial t_n} \right|_{(\mathbf{x}^*, \mathbf{p}^*)} = -c_n(\eta) \left(0 - \frac{2\pi i \eta}{\epsilon} n(N - n) (v_n^*(\eta) - v_{N-n}^*(-\eta)) \right) = 0,$$

as desired. We conclude that the transformed hamiltonians $S \cdot D_n^{\text{cl}}(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau)$ have an equilibrium configuration at $S \cdot (\mathbf{x}^*, \mathbf{p}^*)$. Moreover, the new velocities $c_n(\eta)/(-1/\tau) v_n(\eta)$ also obey the symmetry property (3.23). Hence it follows that for any $B \in \text{PSL}(2, \mathbb{Z})$ the dynamical system $B \cdot D_n^{\text{cl}}(\mathbf{x}, \mathbf{p}, \eta, \epsilon | \tau)$ also has an equilibrium configuration.

3.3. A modular family of equilibrium configurations. We would like to find all classical equilibrium configurations. Actually, we will settle for a little less: we will exploit the preceding modular action to generate a whole family of classical equilibrium configurations starting from a simple well-known ‘seed’ solution $(\mathbf{x}^*, \mathbf{p}^*)$. While it seems to be common lore at least in the ‘non-relativistic’ limit ($\epsilon \propto \eta/g$, $\eta \rightarrow 0$) of the elliptic Calogero–Sutherland system, cf. [Dor99, BT15, BT16], we do not know how to prove that no further (discrete) classical equilibria exist.

Let $\omega \in \mathbb{H}$. Consider the standard classical equilibrium configuration $x_i^{*(1)} = i/N$, $p_j^{*(1)} = 0$, with particles that are fixed equidistantly along the real cycle of the torus. To guarantee a more uniform notation it is prudent to choose an analogous dependence of the parameters on N as

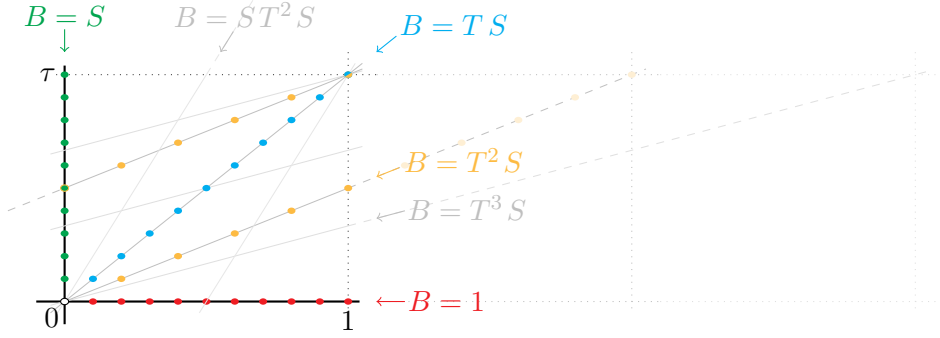


FIGURE 2. Examples of equilibrium positions $x_j^{*(B)}$ for simple $B \in \text{PSL}(2, \mathbb{Z})$, where we take $\tau \in i\mathbb{R}_{>0}$. For freezing, the choices $B = 1$ ($x_j^{*(1)} = j/N$ real) and especially $B = S$ ($x_j^{*(S)} = \tau j/N$ imaginary) are particularly important. In general, equilibrium positions lie equispaced on any line $[0, t]$ (for $t \in \Lambda_\tau \setminus \{0\}$) that does not intersect any other point in Λ_τ .

well. Thus we start from

$$(3.28) \quad \begin{aligned} x_i^{*(1)} &= \frac{i}{N}, & p_j^{*(1)} &= 0, & \tau^{(1)} &= \frac{\omega}{N}, \\ \eta^{(1)} &= \frac{\eta}{N}, & \epsilon^{(1)} &= \frac{\epsilon}{N}, \end{aligned}$$

with the superscript indicating the neutral element $1 \in \text{PSL}(2, \mathbb{Z})$. It is straightforward to check that the associated velocities satisfy the symmetry property (3.23). By applying the S -transformation we obtain the new solution

$$(3.29) \quad \begin{aligned} x_i^{*(S)} &= -\frac{i}{\omega}, & p_j^{*(S)} &= (N+1-2j) \frac{\pi i \eta}{\omega}, & \tau^{(S)} &= -\frac{N}{\omega}, \\ \eta^{(S)} &= -\frac{\eta}{\omega}, & \epsilon^{(S)} &= -\frac{\epsilon}{\omega}, \end{aligned}$$

In this equilibrium configuration the particles are equally spaced along the complex (e.g. imaginary) cycle of the torus, see Fig. 2.

Applying the T -transformation to any solution only shifts the lattice parameter, which, as discussed above, does not change the dynamics. Nevertheless, any subsequent application of the S -transformation propagates the shifted lattice parameter to all other parameters. In particular, this tilts the line in the complex plane on which the equilibrium positions x_i^* lie. The associated spin-chain hamiltonians that we will construct below differ accordingly.

More generally, we obtain a new solution from the ‘seed’ configuration (3.28) for most products of S, T and their inverses; the only duplicate solutions arise from elements related as $B = B' T^n$ for some n , or due to the relations of $\text{PSL}(2, \mathbb{Z})$. Hence the orbit under the modular group produces a whole family of equilibrium configurations,

$$(3.30) \quad \text{PSL}(2, \mathbb{Z}) \cdot (\mathbf{x}^{*(1)}, \mathbf{p}^{*(1)}; \eta^{(1)}, \epsilon^{(1)} | \tau^{(1)}) \subseteq M_{\mathbb{C}}^*.$$

Note that the equilibrium *positions* $\mathbf{x}^*$ are independent of the deformation parameter η , i.e. the same as in the non-relativistic (Calogero–Sutherland–Moser) limit. In contrast, the associated momenta $\mathbf{p}^*$ may depend on η due to the canonical transformation (3.17) needed to preserve the equilibrium condition. Notably, since the non-relativistic limit requires setting $\epsilon = \eta/g$, the shift seems to be required in the elliptic Calogero–Sutherland–Moser case as well.

In conclusion, we have shown how the extended modular action (3.12) on $(\mathbf{x}, \mathbf{p}; \eta, \epsilon | \tau)$ relates different members of the family of Ruijsenaars systems parametrised by $(\eta, \epsilon | \tau) \in \mathbb{C}^2 \times \mathbb{H}$. More precisely, we are free to rescale the coordinates $(\mathbf{x}, \mathbf{p})$ classically; $\mathbf{x}$ quantum-mechanically) and other parameters in such a way that the resulting system is defined on the same lattice. Hence physically *inequivalent* Ruijsenaars systems are parametrised by the quotient $(\mathbb{C}^2 \times$

$\mathbb{H}/\mathrm{PSL}(2, \mathbb{Z})$. Put differently, for any fixed $\tau \in \mathbb{H}/\mathrm{PSL}(2, \mathbb{Z})$ in the fundamental domain, the modular action generates a family of physically *equivalent* Ruijsenaars systems. At the classical level, this action allows one to construct a modular family of (discrete) equilibrium configurations.

4. FREEZING

A suitable expansion of our quantum many-body system with spins yields a family of commuting operators that act (nontrivially) on spins only via a method called ‘freezing’ [Pol93]. This is a two-step process,

$$(4.1) \quad \begin{array}{ccccc} \text{quantum} & & \text{hybrid} & & \text{long-range} \\ \text{many-body system} & \longmapsto & \text{many-body system} & \longmapsto & \text{(quantum) spin chain.} \\ \text{with spins} & & & & \end{array}$$

Starting from a (quantum) spin-Ruijsenaars system, one takes a limit in which the potential energy dominates the kinetic energy. It can be viewed as a strong-coupling or partial (semi)classical limit. In this limit, the system decouples into a ‘hybrid system’, consisting of a classical Ruijsenaars–Schneider system that governs the dynamics (times the identity on spins) plus a quantum part with spin interactions (but no difference/differential operators). The dynamics completely disappears at any classical equilibrium configuration, yielding a system of quantum-mechanical spins at fixed positions: this is the spin chain.

The aim of this section is to make this process precise. We follow [Ugl95, LPS22], supplemented by further insights from [MZ23a] for the elliptic case, and [Cha24, MV24, LRS24] for the setting of deformation quantisation.

4.1. Formalism: deformation quantisation. In order to relate the quantum Ruijsenaars system (2.3) to its classical counterpart (3.3), we need to have a way to take the classical limit of Ruijsenaars systems. The appropriate setting is provided by deformation quantisation [BFF⁺78a, BFF⁺78b], cf. [Kon03] and [Eti07]. For the setting with spins we follow [Cha24, MV24, LRS24].

To warm up, we start with the scalar case. We interpret the difference operators (2.3) as elements $D_n \in \mathcal{A}_\hbar$ of the associative algebra

$$(4.2) \quad \mathcal{A}_\hbar := \mathrm{Fun}(\mathbf{x})[\Gamma_1^{\pm 1}, \dots, \Gamma_N^{\pm 1}] \otimes \mathbb{C}[[\hbar]],$$

consisting of Laurent polynomials in the difference operators Γ_j with coefficients that are meromorphic functions in $x_1, \dots, x_N$ times a formal power series in $\hbar$.^{5,6} From the formal power series

$$(4.3) \quad (\Gamma_j f)(\mathbf{x}) = f(x_1, \dots, x_j - i\epsilon\hbar, \dots, x_N) = \sum_{k \geq 0} \frac{1}{k!} (-i\epsilon)^k \partial_j^k f(\mathbf{x}) \hbar^k \in \mathcal{A}_\hbar$$

one obtains the nontrivial commutation relations

$$(4.4a) \quad -i\hbar^{-1} [f(\mathbf{x}), \Gamma_j] = \epsilon \partial_j f(\mathbf{x}) + O(\hbar)$$

for $\mathcal{A}_\hbar$. In particular, taking $f(\mathbf{x}) = x_i$ a coordinate function gives

$$(4.4b) \quad [x_i, \Gamma_j] = i\hbar\epsilon \delta_{ij} \Gamma_j,$$

which is an intermediate version of the Heisenberg commutation relations $[x_i, \hat{p}_j] = i\hbar \delta_{ij}$ (additive notation) and the Weyl-algebra relations $e^{ix_i} \Gamma_j = e^{\epsilon\hbar} \Gamma_j e^{ix_i}$ (fully multiplicative notation).

⁵ To be precise, by $\mathrm{Fun}(\mathbf{x})[\Gamma_1^{\pm 1}, \dots, \Gamma_N^{\pm 1}]$ we mean the vector space $\mathrm{Fun}(\mathbf{x}) \otimes \mathbb{C}[\Gamma_1^{\pm 1}, \dots, \Gamma_N^{\pm 1}]$ with product induced by $f(\mathbf{x}) \Gamma_i g(\mathbf{x}) \Gamma_j = f(\mathbf{x}) g(\mathbf{x} - i\hbar\epsilon e_i) \Gamma_i \Gamma_j$, cf. (4.3)–(4.4). This is extended $\mathbb{C}[[\hbar]]$ -bilinearly to $\mathcal{A}_\hbar$.

⁶ The difference operators can (formally) be expressed as $\Gamma_j = \exp(\epsilon \hat{p}_j)$. While quantum-mechanically $\hat{p}_j = -i\hbar \partial_{x_j}$, we emphasise that the latter $\hbar$ is viewed as a part of the operator $\hat{p}_j$ rather than $\mathbb{C}[[\hbar]]$. However, when $\hat{p}_j$ acts on a function f , the resulting $\partial_j f(\mathbf{x}) \in \mathrm{Fun}(\mathbf{x})$ has coefficient $-i\hbar \in \mathbb{C}[[\hbar]]$, see e.g. (4.4b).

The commutative algebra $\mathcal{A}_0 = \text{Fun}(\mathbf{x})[\gamma_1^{\pm 1}, \dots, \gamma_N^{\pm 1}]$ from §3, with $\gamma_j = e^{\epsilon p_j}$, is the classical limit of $\mathcal{A}_\hbar$ in the following precise sense. Since the commutator (4.4b) is of order $\hbar$, the quotient $\mathcal{A}_\hbar/\hbar\mathcal{A}_\hbar$ is also a commutative algebra. It is isomorphic to $\mathcal{A}_0$ via the $\mathbb{C}$ -linear map

$$(4.5) \quad \mathcal{A}_\hbar/\hbar\mathcal{A}_\hbar \xrightarrow{\sim} \mathcal{A}_0, \quad f(\mathbf{x}) \mapsto f(\mathbf{x}), \quad \Gamma_i \mapsto \gamma_i \quad (\text{i.e. } \hat{p}_i \mapsto p_i).$$

This exhibits $\mathcal{A}_\hbar$ as a (flat, formal) deformation of $\mathcal{A}_0$. Now choose an identification of $\mathbb{C}[[\hbar]]$ -modules

$$(4.6) \quad c_\hbar: \mathcal{A}_\hbar \xrightarrow{\sim} \mathcal{A}_0[[\hbar]]$$

that reduces mod $\hbar$ to (4.5). Concretely, this isomorphism boils down to a choice of a (normal) ordering of the quantum operators. In turn, $c_\hbar$ allows one to transport the (non-commutative) product on $\mathcal{A}_\hbar$ to $\mathcal{A}_0[[\hbar]]$, equipping the latter with the (associative, $\mathbb{C}[[\hbar]]$ -bilinear) Moyal star-product

$$(4.7) \quad a \star b := c_\hbar(c_\hbar^{-1}(a) c_\hbar^{-1}(b)) = \sum_{k \geq 0} m_k(a, b) \hbar^k, \quad m_0(a, b) = ab,$$

Each coefficient function m_k , which in general are non-zero due to (4.3), in the formal power series (4.7) is itself a product on $\mathcal{A}_0$, with m_0 the original (commutative) product. At the next order in $\hbar$, compatibility with (4.4) requires the bracket on $\mathcal{A}_0$ given by

$$(4.8) \quad \{f, g\} := -i(m_1(f, g) - m_1(g, f)) = -i\hbar^{-1} c_\hbar([c_\hbar^{-1}(f), c_\hbar^{-1}(g)]) \mod \hbar$$

to obey the Poisson relations (3.1b) of the (scalar) Ruijsenaars–Schneider system. Note that (4.8) is independent of the choice of quantisation scheme $c_\hbar^{-1}$ since nonvanishing commutators (4.4) are already of order $\hbar$. The *classical limit* corresponds to the composition $\mathcal{A}_\hbar \xrightarrow{\sim} \mathcal{A}_\hbar/\hbar\mathcal{A}_\hbar \xrightarrow{\sim} \mathcal{A}_0$, which amounts to the map

$$(4.9) \quad c_0 = c_\hbar|_{\hbar=0}: \mathcal{A}_\hbar \longrightarrow \mathcal{A}_0, \quad f(\mathbf{x}) \mapsto f(\mathbf{x}), \quad \Gamma_i \mapsto \gamma_i, \quad \hbar \mapsto 0.$$

Equipping the quantum space $\mathcal{A}_\hbar$ with the rescaled commutator $[\cdot, \cdot]_\hbar := -i\hbar^{-1}[\cdot, \cdot]$ would turn (4.9) into a Poisson-algebra homomorphism, but we prefer to work with the ordinary commutator to keep all factors of $\hbar$ explicit.

We are now ready to discuss the spin case. Let $r \geq 2$ and upgrade $\mathcal{A}_\hbar$ to its matrix-valued variant⁷

$$(4.10) \quad \tilde{\mathcal{A}}_\hbar := \text{Fun}(\mathbf{x}) \otimes \text{Mat}(r^N, \mathbb{C}) \otimes \mathbb{C}[\Gamma_1^{\pm 1}, \dots, \Gamma_N^{\pm 1}] \otimes \mathbb{C}[[\hbar]],$$

which again is non-commutative and thus has a nontrivial Poisson bracket given by the commutator. However, its classical version

$$(4.11) \quad \tilde{\mathcal{A}}_0 := \text{Fun}(\mathbf{x}) \otimes \text{Mat}(r^N, \mathbb{C})[\gamma_1^{\pm 1}, \dots, \gamma_N^{\pm 1}],$$

is no longer a commutative algebra, and hence unsuitable as the phase space of an (ordinary) Hamiltonian system. Proceeding as before, we extend (4.9) to the surjective algebra homomorphism

$$(4.12) \quad \tilde{c}_0: \tilde{\mathcal{A}}_\hbar \longrightarrow \tilde{\mathcal{A}}_0, \quad f(\mathbf{x}) \mapsto f(\mathbf{x}), \quad M \mapsto M, \quad \Gamma_i \mapsto \gamma_i, \quad \hbar \mapsto 0,$$

with $M \in \text{Mat}(r^N, \mathbb{C})$. Observe that this is only a partial classical limit: the dependence on $\mathbf{x}$ and $\mathbf{p}$ becomes classical, but the spin part M remains fully quantum mechanical. Like before, its kernel is $\hbar\tilde{\mathcal{A}}_\hbar$, but this time the corresponding map $\tilde{\mathcal{A}}_\hbar/\hbar\tilde{\mathcal{A}}_\hbar \xrightarrow{\sim} \tilde{\mathcal{A}}_0$ is an isomorphism of *non-commutative* algebras. For our purposes, a suitable candidate for the classical phase space is the centre $Z(\tilde{\mathcal{A}}_0)$, which can be identified with $\mathcal{A}_0 \cong Z(\tilde{\mathcal{A}}_0)$ through the inclusion $a \mapsto a \text{ id}$. It acquires a Poisson bracket as in (4.8): for any $a, b \in Z(\tilde{\mathcal{A}}_0)$ we set

$$(4.13) \quad \{a, b\} := -i\hbar^{-1} \tilde{c}_\hbar([\tilde{c}_\hbar^{-1}(a), \tilde{c}_\hbar^{-1}(b)]) \mod \hbar,$$

⁷ One may replace $\text{Mat}(r^N, \mathbb{C}) \cong \text{End}(V^{\otimes N})$ for $V \cong \mathbb{C}^r$ by any representation U of S_N , or, if one prefers to work abstractly rather than in a representation, the group algebra $\mathbb{C}S_N$, cf. e.g. [Cha24].

retrieving the Poisson structure (4.8) (times the identity matrix). When $a \in Z(\tilde{\mathcal{A}}_0)$ but $\tilde{b} \in \tilde{\mathcal{A}}_0$, then a does not see the matrix structure of $\tilde{b}$, so the commutator $c_\hbar([\tilde{c}_\hbar^{-1}(a), \tilde{c}_\hbar^{-1}(\tilde{b})])$ remains of order $\hbar$. Hence the formula (4.13) can be used to define an action of $Z(\tilde{\mathcal{A}}_0)$ on $\tilde{\mathcal{A}}_0$ by derivations, given by $a \cdot \tilde{b} := \{a, \tilde{b}\}$ for $a \in \mathcal{A}_0 \cong Z(\tilde{\mathcal{A}}_0)$ and $\tilde{b} \in \tilde{\mathcal{A}}_0$. This plays well with the Poisson structure (4.13) of $Z(\tilde{\mathcal{A}}_0)$, i.e. $\{a, a'\} \cdot \tilde{b} = a \cdot (a' \cdot \tilde{b}) - a' \cdot (a \cdot \tilde{b})$, thus turning $\tilde{\mathcal{A}}_0$ into a $Z(\tilde{\mathcal{A}}_0)$ -Poisson module.⁸ Such an algebra, which is a (simple) Poisson module of finite rank over its own centre, was studied in [MV24, LRS24]. The authors of [LRS24] called it a *Poisson–Azuyama algebra*, and the dynamical system that it defines a *hybrid* dynamical system.

4.2. Step one: hybrid expansion.

4.2.1. *Quantum spinless case.* We first consider the quantum model without spins. Recall that

$$(4.14) \quad [D_n, D_m] = 0, \quad D_n = \sum_{\substack{I \subset \{1, \dots, N\} \\ |I|=n}} A_I(\mathbf{x}; \eta) \Gamma_I, \quad \Gamma_I = \prod_{i \in I} \Gamma_i.$$

As elements in $\mathcal{A}_\hbar$ we can directly compute

$$(4.15) \quad c_0(D_n) = D_n^{\text{cl}} = \sum_{\substack{I \subset \{1, \dots, N\} \\ |I|=n}} A_I(\mathbf{x}; \eta) \gamma_I, \quad \gamma_I = \prod_{i \in I} e^{\epsilon p_i},$$

which are the Ruijsenaars–Schneider functions (3.3). In order to analyse the lowest orders in $\hbar$ of the commutator we first expand the product $D_n D_m$ in $\hbar$. For brevity we suppress the details of the summation ranges $I, J \subseteq \{1, \dots, N\}$ with $|I| = n$ and $|J| = m$ in the following, as well as the argument η of the coefficients. Then

$$(4.16) \quad \begin{aligned} D_n D_m &= \sum_{I, J} A_J(\mathbf{x}) \Gamma_I A_J(\mathbf{x}) \Gamma_J \\ &= \sum_{I, J} A_I(\mathbf{x}) A_J \left(\mathbf{x} - i \epsilon \hbar \sum_{i \in I} e_i \right) \Gamma_I \Gamma_J \\ &= \sum_{I, J} A_I(\mathbf{x}) \left(A_J(\mathbf{x}) - i \epsilon \hbar \sum_{i \in I} \partial_i A_J(\mathbf{x}) - \frac{\epsilon^2 \hbar^2}{2} \sum_{i, i' \in I} \partial_i \partial_{i'} A_J(\mathbf{x}) + O(\hbar^3) \right) \Gamma_I \Gamma_J. \end{aligned}$$

The sum at order $\hbar^2$ is $\sum_{i, i' \in I} \partial_i \partial_{i'} = (\sum_{i \in I} \partial_i)^2$ applied to $A_J(\mathbf{x})$.

Let us further suppress the arguments $\mathbf{x}$ of the coefficients A_I and A_J . Since these functions commute with each other, and the difference operators Γ_I, Γ_J do so too, we get

$$(4.17) \quad \begin{aligned} 0 = [D_n, D_m] &= -i \epsilon \hbar \sum_{I, J} \left(A_I \sum_{i \in I} \partial_i A_J - A_J \sum_{j \in J} \partial_j A_I \right) \Gamma_I \Gamma_J \\ &\quad - \frac{\epsilon^2 \hbar^2}{2} \sum_{I, J} \left(A_I \sum_{i, i' \in I} \partial_i \partial_{i'} A_J - A_J \sum_{j, j' \in J} \partial_j \partial_{j'} A_I \right) \Gamma_I \Gamma_J \\ &\quad + O(\hbar^3). \end{aligned}$$

⁸ As shown in [MV24], in general the natural candidate for the generalisation of the classical phase space to the matrix-valued (spin)-setting is not $Z(\tilde{\mathcal{A}}_0)$, but rather the slightly bigger $\Pi(\tilde{\mathcal{A}}_0) := Z(\tilde{\mathcal{A}}_0) \times (\tilde{\mathcal{A}}_0 / Z(\tilde{\mathcal{A}}_0))$, which inherits a Poisson structure and compatible commutative product from $\tilde{\mathcal{A}}_\hbar$ by considering it as the quotient $(Z(\tilde{\mathcal{A}}_0) + \hbar \tilde{\mathcal{A}}_0) / \hbar (Z(\tilde{\mathcal{A}}_0) + \hbar \tilde{\mathcal{A}}_0)$. It moreover defines a $\Pi(\tilde{\mathcal{A}}_0)$ -Poisson module structure on $\tilde{\mathcal{A}}_0$. In our case, the product on $\Pi(\tilde{\mathcal{A}}_0)$ simplifies due to the fact that for all $a, b \in Z(\tilde{\mathcal{A}}_0)$ the product $ab \in Z(\tilde{\mathcal{A}}_0)$, receiving no contributions from $m_2(a, b)$ as that is central. In the language of [LRS24], $\tilde{\mathcal{A}}_0$ is *flat*. The $\Pi(\tilde{\mathcal{A}}_0)$ -Poisson module can then be restricted to a $Z(\tilde{\mathcal{A}}_0)$ -Poisson module, resulting in the structure introduced above. Note that the dynamical system defined by the former is fully classical – including spins –, which is not the setting we need in order to obtain (quantum) spin-chain hamiltonians.

From the terms linear in $\hbar$,

$$(4.18) \quad -i\hbar^{-1} [D_n, D_m] = -\epsilon \sum_{I,J} \left(A_I \sum_{i \in I} \partial_i A_J - A_J \sum_{j \in J} \partial_j A_I \right) \Gamma_I \Gamma_J + O(\hbar),$$

we get

$$(4.19) \quad c_0(-i\hbar^{-1} [D_n, D_m]) = -\epsilon \sum_{I,J} \left(A_I \sum_{i \in I} \partial_i A_J - A_J \sum_{j \in J} \partial_j A_I \right) \gamma_I \gamma_J.$$

This matches direct computation of the Poisson bracket

$$(4.20) \quad \begin{aligned} \{D_n^{\text{cl}}, D_m^{\text{cl}}\} &= \sum_{i,j=1}^N \left(\frac{\partial D_n^{\text{cl}}}{\partial x_i} \frac{\partial D_m^{\text{cl}}}{\partial \gamma_j} \{x_i, \gamma_j\} + \frac{\partial D_n^{\text{cl}}}{\partial \gamma_i} \frac{\partial D_m^{\text{cl}}}{\partial x_j} \{\gamma_i, x_j\} \right) \\ &= \sum_{I,J} \left(\sum_{i=1}^N \partial_i A_I \gamma_I \sum_{j \in J} A_J \gamma_{J \setminus \{j\}} \times \epsilon \gamma_j \delta_{ij} + \sum_{i \in I} A_I \gamma_{I \setminus \{i\}} \sum_{j=1}^N \partial_j A_J \gamma_J \times -\epsilon \gamma_i \delta_{ji} \right), \end{aligned}$$

where the second equality uses the Poisson bracket (3.1b). Thus we verified that

$$(4.21) \quad c_0(-i\hbar^{-1} [D_n, D_m]) = \{D_n^{\text{cl}}, D_m^{\text{cl}}\} = 0,$$

in line with (4.8).

More generally, the commutator (4.17) vanishes to all orders in $\hbar$. At higher orders this yields non-trivial identities for the coefficients $A_I(\mathbf{x}; \eta)$ that will be helpful in the following.

4.2.2. Quantum case with spin. Now consider a quantum-mechanical elliptic Ruijsenaars system with spins, described by some hierarchy of matrix-valued difference operators that commute. Let us consider the expansion of these operators in the *explicitly* appearing $\hbar$,

$$(4.22) \quad \tilde{D}_{\pm n} = \sum_I \tilde{A}_I(\mathbf{x}) \Gamma_I^{\pm 1} = \sum_{d \geq 0} \tilde{D}_{\pm n}^{(d)} \hbar^d, \quad \tilde{D}_{\pm n}^{(d)} := \sum_I \tilde{A}_{\pm I}^{(d)}(\mathbf{x}) \Gamma_I^{\pm 1},$$

where we use tildes to indicate matrix valuedness. For the present discussion, the explicit form of the coefficients following from §2 is not relevant, and only distracts from the argument. We will compute some examples of the $\tilde{D}_{\pm n}^{(1)}$ in §4.4. For now, we only borrow from §2 the assumption that the matrix-valued coefficients do not contain any further difference operators, i.e. $\tilde{A}_I(\mathbf{x}) \in \text{Fun}(\mathbf{x}) \otimes \text{Mat}(r^N, \mathbb{C})$, and are such that

$$(4.23) \quad \tilde{A}_I(\mathbf{x}) = A_I(\mathbf{x}) \text{id} + O(\hbar), \quad \text{i.e.} \quad \tilde{A}_I^{(0)}(\mathbf{x}) = A_I(\mathbf{x}).$$

Then $\tilde{D}_n^{(0)} = D_n \text{id}$, which is still quantum mechanical through the implicit $\hbar$ in the difference operators Γ_i . The replacement of Γ_I by γ_I will be achieved by applying the map $\tilde{c}_0$. Although $\tilde{c}_0(\tilde{D}_n^{(0)}) = D_n^{\text{cl}} \text{id}$ could be viewed as a classical quantity, for $n \neq N$ the $\tilde{D}_{\pm n}^{(d)}$ with $d \geq 1$ will contain deformed spin permutations (quantum R -matrices) in addition to the difference operators Γ_i . Even after applying the (partial) classical limit $\tilde{c}_0$, they remain fully quantum mechanical in terms of spins. To emphasise that we do *not* expand the implicit $\hbar$ in Γ_I (cf. footnote 6), we call (4.22) a *hybrid* expansion.

Pick two such operators, $\tilde{D}_n = \sum_I \tilde{A}_I(\mathbf{x}) \Gamma_I$ and $\tilde{D}_m = \sum_J \tilde{A}_J(\mathbf{x}) \Gamma_J$, where, as before, sums over n - and m - element subsets I and J , respectively, are understood. From the hybrid

expansion of their commutator we obtain the following refinement of (4.17):

$$\begin{aligned}
0 = [\tilde{D}_n, \tilde{D}_m] &= \sum_{I,J} \left(\tilde{A}_I(\mathbf{x}) \tilde{A}_J \left(\mathbf{x} - i\epsilon \hbar \sum_{i \in I} e_i \right) - \tilde{A}_J(\mathbf{x}) \tilde{A}_I \left(\mathbf{x} - i\epsilon \hbar \sum_{j \in J} e_j \right) \right) \Gamma_I \Gamma_J \\
(4.24) \quad &= \sum_{I,J} [\tilde{A}_I, \tilde{A}_J] \Gamma_I \Gamma_J - i\epsilon \hbar \sum_{I,J} \left(\tilde{A}_I \sum_{i \in I} \partial_i \tilde{A}_J - \tilde{A}_J \sum_{j \in J} \partial_j \tilde{A}_I \right) \Gamma_I \Gamma_J \\
&\quad - \frac{\epsilon^2 \hbar^2}{2} \sum_{I,J} \left(\tilde{A}_I \sum_{i,i' \in I} \partial_i \partial_{i'} \tilde{A}_J - \tilde{A}_J \sum_{j,j' \in J} \partial_j \partial_{j'} \tilde{A}_I \right) \Gamma_I \Gamma_J + O(\hbar^3).
\end{aligned}$$

If (4.23) then $\tilde{c}_0(\tilde{D}_n) = D_n \text{id} \in Z(\tilde{\mathcal{A}}_0)$. Moreover, the terms of order $\hbar^0$ in (4.24) vanish, and the part of (4.24) linear in $\hbar$ becomes precisely (4.20) (times id), which implies that

$$(4.25) \quad \tilde{c}_0(-i\hbar^{-1}[\tilde{D}_n, \tilde{D}_m]) = \{\tilde{c}_0(D_n), \tilde{c}_0(D_m)\} \text{id} = 0.$$

We stress that the right-hand side features the Poisson bracket of the *scalar* Ruijsenaars hamiltonians, times the identity on spins, as in (4.13). In fact, by virtue of (4.17) the part linear in $\hbar$ of (4.24) with (4.23) vanishes even *before* applying $\tilde{c}_0$. Hence the first non-trivial terms occur at $\hbar^2$. They are given by

$$\begin{aligned}
0 = \hbar^{-2} [\tilde{D}_n, \tilde{D}_m] &= \sum_{I,J} \left([\tilde{A}_I^{(2)}, \tilde{A}_J^{(0)}] + [\tilde{A}_I^{(1)}, \tilde{A}_J^{(1)}] + [\tilde{A}_I^{(0)}, \tilde{A}_J^{(2)}] \right) \Gamma_I \Gamma_J \\
&\quad - i\epsilon \sum_{I,J} \left(\tilde{A}_I^{(0)} \sum_{i \in I} \partial_i \tilde{A}_J^{(1)} - \tilde{A}_J^{(1)} \sum_{j \in J} \partial_j \tilde{A}_I^{(0)} \right) \Gamma_I \Gamma_J \\
(4.26) \quad &\quad - i\epsilon \sum_{I,J} \left(\tilde{A}_I^{(1)} \sum_{i \in I} \partial_i \tilde{A}_J^{(0)} - \tilde{A}_J^{(0)} \sum_{j \in J} \partial_j \tilde{A}_I^{(1)} \right) \Gamma_I \Gamma_J \\
&\quad - \frac{1}{2} \epsilon^2 \sum_{I,J} \left(\tilde{A}_I^{(0)} \sum_{i,i' \in I} \partial_i \partial_{i'} \tilde{A}_J^{(0)} - \tilde{A}_J^{(0)} \sum_{j,j' \in J} \partial_j \partial_{j'} \tilde{A}_I^{(0)} \right) \Gamma_I \Gamma_J \\
&\quad + O(\hbar).
\end{aligned}$$

The first and third matrix commutator in the first line of the right-hand side vanish due to (4.23). The terms linear in ϵ on the next two lines come from the first-order bracket m_1 , and will give rise to the Poisson bracket (4.13) upon applying $\tilde{c}_0$. The coefficient of ϵ^2 on the fourth line, which is the contribution from the second-order bracket

$$(4.27) \quad \{\tilde{c}_0(\tilde{D}_n), \tilde{c}_0(\tilde{D}_m)\}_2 = m_2(\tilde{c}_0(\tilde{D}_n), \tilde{c}_0(\tilde{D}_m)) - m_2(\tilde{c}_0(\tilde{D}_m), \tilde{c}_0(\tilde{D}_n)),$$

vanishes thanks to the ϵ^2 -term of the identity (4.17) from the spinless case. This is an example of the fact that $\tilde{\mathcal{A}}_0$ is flat in the sense of [LRS24] (cf. footnote 8 on p. 15) in a strong sense: (4.27) does not just lie in $Z(\tilde{\mathcal{A}}_0)$, but it vanishes. Therefore, comparing with (4.20) we conclude that, after taking the classical limit,

$$\begin{aligned}
0 &= \tilde{c}_0(\hbar^{-2} [\tilde{D}_n, \tilde{D}_m]) \\
(4.28) \quad &= \{\tilde{c}_0(\tilde{D}_n^{(0)}), \tilde{c}_0(\tilde{D}_m^{(1)})\} + \{\tilde{c}_0(\tilde{D}_n^{(1)}), \tilde{c}_0(\tilde{D}_m^{(0)})\} + [\tilde{c}_0(\tilde{D}_n^{(1)}), \tilde{c}_0(\tilde{D}_m^{(1)})] \\
&= \{D_n^{\text{cl}}, \tilde{c}_0(\tilde{D}_m^{(1)})\} + \{\tilde{c}_0(\tilde{D}_n^{(1)}), D_m^{\text{cl}}\} + [\tilde{c}_0(\tilde{D}_n^{(1)}), \tilde{c}_0(\tilde{D}_m^{(1)})].
\end{aligned}$$

In particular, for $m = N$, noting $\tilde{D}_N = D_N \text{id}$ (so that $\tilde{D}_N^{(d)} = 0$ for $d > 1$), we obtain the non-trivial identity

$$(4.29) \quad 0 = \{\tilde{c}_0(\tilde{D}_n^{(1)}), \tilde{c}_0(D_N)\} = \tilde{c}_0(D_N) \sum_{i=1}^N \frac{\partial \tilde{c}_0(\tilde{D}_n^{(1)})}{\partial x_j} \implies \sum_{i=1}^N \frac{\partial \tilde{c}_0(\tilde{D}_n^{(1)})}{\partial x_j} = 0,$$

which will come in handy momentarily.

4.3. Step two: evaluation. With these hybrid expansions in place, we now are ready to perform the second part of freezing, by evaluating (4.28) at one of the classical equilibria we obtained in §3.3. We will want to include the case with spins. To this end, note that the dynamical parameter $\vec{a}$ is readily included in our treatment of the equilibria since it occurs in the same way as the x_i and η . Thus, $\vec{a}^{*(1)} = \vec{a}/N$ for (3.28) and $\vec{a}^{*(S)} = -\vec{a}/\omega$ for (3.29). Let us introduce ‘evaluation’ maps

$$(4.30) \quad \text{ev}_B : (\mathbf{x}, \mathbf{p}; \eta, \epsilon, \vec{a} \mid \tau) \longmapsto (\mathbf{x}^{*(B)}, \mathbf{p}^{*(B)}; \eta^{*(B)}, \epsilon^{*(B)}, \vec{a}^{*(B)} \mid \tau^{(B)}) \\ = B \cdot (\mathbf{x}^{*(1)}, \mathbf{p}^{*(1)}; \eta^{*(1)}, \epsilon^{*(1)}, \vec{a}^{*(1)} \mid \tau^{(1)}), \quad B \in \text{PSL}(2, \mathbb{Z}),$$

that specialise the parameters to the equilibrium generated by $B \in \text{PSL}(2, \mathbb{Z})$. These maps may act on operators $\tilde{O}$ by $\text{ev}_B \circ \tilde{O}$. We will write $\tilde{O}_1 \stackrel{\text{ev}_B}{=} \tilde{O}_2$ as a shorthand for $\text{ev}_B \circ \tilde{O}_1 = \text{ev}_B \circ \tilde{O}_2$.

We can now compute what happens after evaluation to the first two Poisson brackets in (4.28):

$$(4.31) \quad \{D_n^{\text{cl}}, \tilde{c}_0(\tilde{D}_m^{(1)})\} = \sum_{i,j=1}^N \left(\frac{\partial D_n^{\text{cl}}}{\partial x_i} \frac{\partial \tilde{c}_0(\tilde{D}_m^{(1)})}{\partial \gamma_j} \{x_i, \gamma_j\} + \frac{\partial D_n^{\text{cl}}}{\partial \gamma_i} \frac{\partial \tilde{c}_0(\tilde{D}_m^{(1)})}{\partial x_j} \{\gamma_i, x_j\} \right) \\ \stackrel{\text{ev}_B}{=} \sum_{i,j=1}^N \frac{\partial D_n^{\text{cl}}}{\partial \gamma_i} \frac{\partial \tilde{c}_0(\tilde{D}_m^{(1)})}{\partial x_j} \{\gamma_i, x_j\} \\ \stackrel{\text{ev}_B}{=} -v_n^* \sum_{i,j=1}^N \frac{\partial \tilde{c}_0(\tilde{D}_m^{(1)})}{\partial x_j} = 0,$$

by first recognising the (i -independent) velocities (3.20a) and then the identity (4.29). Rearranging (4.28) and applying the evaluation map then yields

$$(4.32) \quad [\tilde{c}_0(\tilde{D}_n^{(1)}), \tilde{c}_0(\tilde{D}_m^{(1)})] = -\{D_n^{\text{cl}}, \tilde{c}_0(\tilde{D}_m^{(1)})\} - \{\tilde{c}_0(\tilde{D}_n^{(1)}), D_m^{\text{cl}}\} \stackrel{\text{ev}_B}{=} 0.$$

Since after taking the classical limit there are no more difference operators, the matrix-valued operators

$$(4.33) \quad H_{n,B} := \text{ev}_B(\tilde{c}_0(\tilde{D}_n^{(1)}))$$

act trivially *on functions*. They can thus be restricted to act on $V^{\otimes N}$ only, and hence define hamiltonians of a long-range spin chain that is integrable in the sense that

$$(4.34) \quad [H_{n,B}, H_{m,B}] = 0.$$

4.4. Explicit spin-chain hamiltonians. Let us compute the first few spin chain hamiltonians from the spin Ruijsenaars operators in (2.20). Starting with $\tilde{D}_1$ from (2.21), we perform the hybrid expansion (4.22) in the *explicitly* appearing $\hbar$ as

$$(4.35) \quad \tilde{D}_1 = \sum_{j=1}^N A_j(\mathbf{x}) P_{(1 \dots j)}(\mathbf{x})^{-1} P_{(1 \dots j)}(x_1, \dots, x_j - i\hbar\epsilon, \dots, x_N) \Gamma_j \\ = \tilde{D}_1^{(0)} + \hbar \tilde{D}_1^{(1)} + O(\hbar^2).$$

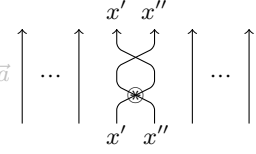
The first few coefficients are given by

$$(4.36a) \quad \tilde{D}_1^{(0)} := \sum_{j=1}^N A_j(\mathbf{x}) \Gamma_j = D_1 \text{id} \in Z(\tilde{\mathcal{A}}_0),$$

which satisfies (4.23), and

$$(4.36b) \quad \tilde{D}_1^{(1)} := \sum_{j=2}^N \tilde{A}_j(\mathbf{x}) \Gamma_j, \quad \tilde{A}_j(\mathbf{x}) = i\epsilon A_j(\mathbf{x}) \sum_{i=1}^{j-1} P_{(i+1 \dots j)}(\mathbf{x})^{-1} h_{i,i+1}(x_i - x_j) P_{(i+1 \dots j)}(\mathbf{x}),$$

where $\tilde{A}_1(\mathbf{x}) = 0$ and for $j \geq 2$ we introduced the nearest-neighbour spin interaction

$$(4.37) \quad h_{i,i+1}(u) := P_{i,i+1}(-u) P'_{i,i+1}(u) = \vec{a} \left| \begin{array}{c} \uparrow \\ \vdots \\ \uparrow \end{array} \right| \left| \begin{array}{c} \uparrow \\ \vdots \\ \uparrow \end{array} \right| \left| \begin{array}{c} \uparrow \\ \vdots \\ \uparrow \end{array} \right| \left| \begin{array}{c} \uparrow \\ \vdots \\ \uparrow \end{array} \right| \left| \begin{array}{c} \uparrow \\ \vdots \\ \uparrow \end{array} \right| \quad u = x' - x'',$$


with ‘ $\otimes$ ’ indicating the derivative of the R -matrix in our graphical notation. We emphasise again that these are still quantum-mechanical operators, through the implicit $\hbar$ in Γ_j as well as, for $d \geq 1$, the deformed spin interactions.

Similarly we compute the hybrid expansion of $\tilde{D}_{-1}$ from (2.23),

$$(4.38) \quad \tilde{D}_{-1} = \tilde{D}_{-1}^{(0)} + \hbar \tilde{D}_{-1}^{(1)} + O(\hbar^2),$$

with coefficients

$$(4.39) \quad \begin{aligned} \tilde{D}_{-1}^{(0)} &:= \sum_{i=1}^N A_{-i}(\mathbf{x}) \Gamma_i^{-1} = D_{-1} \text{id} \in Z(\tilde{\mathcal{A}}_0), \\ \tilde{D}_{-1}^{(1)} &:= i \epsilon \sum_{i=1}^{N-1} A_{-i}(\mathbf{x}) \sum_{j=i+1}^N P_{(j+1 \dots i)}(\mathbf{x})^{-1} h_{j-1,j}(x_i - x_j) P_{(j+1 \dots i)}(\mathbf{x}) \Gamma_i^{-1}. \end{aligned}$$

Again the coefficients take the form (4.23), so we can use the results from the previous section to conclude that, for any $B \in \text{PSL}(2, \mathbb{Z})$,

$$(4.40) \quad [\text{ev}_B(\tilde{c}_0(\tilde{D}_1^{(1)})), \text{ev}_B(\tilde{c}_0(\tilde{D}_{-1}^{(1)})] = 0.$$

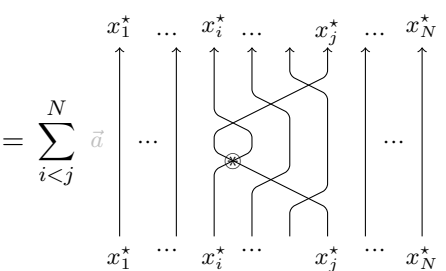
Remember from §3.2 that the summands of the first Ruijsenaars operator D_1 all coincide in the classical limit at equilibrium: for any j ,

$$(4.41a) \quad \tilde{c}_0(\epsilon A_j(\mathbf{x}) \Gamma_j / v_1) \stackrel{\text{ev}_B}{=} \epsilon A_j(\mathbf{x}^*) \gamma_j^* / v_1^* = 1.$$

Similarly, for $n = -1$ and any j

$$(4.41b) \quad \tilde{c}_0(\epsilon A_{-j}(\mathbf{x}) \Gamma_j^{-1} / v_{-1}) \stackrel{\text{ev}_B}{=} \epsilon A_{-j}(\mathbf{x}^*) \gamma_j^{*-1} / v_{-1}^* = 1, \quad v_{-1}^* = v_{N-1}^* / v_N^*.$$

We are thus led to define the normalised ‘chiral’ spin-chain hamiltonians

$$(4.42) \quad \begin{aligned} \bar{H}_{1,B} &:= \text{ev}_B \left(\frac{\tilde{c}_0(\tilde{D}_1^{(1)})}{i v_1^*} \right) = \sum_{j=2}^N \sum_{i=1}^{j-1} P_{(i+1 \dots j)}(\mathbf{x}^*)^{-1} h_{i,i+1}(x_i^* - x_j^*) P_{(i+1 \dots j)}(\mathbf{x}^*) \\ &= \sum_{i < j}^N \vec{a} \left| \begin{array}{c} \uparrow \\ \vdots \\ \uparrow \end{array} \right| \left| \begin{array}{c} \uparrow \\ \vdots \\ \uparrow \end{array} \right| \left| \begin{array}{c} \uparrow \\ \vdots \\ \uparrow \end{array} \right| \left| \begin{array}{c} \uparrow \\ \vdots \\ \uparrow \end{array} \right| \left| \begin{array}{c} \uparrow \\ \vdots \\ \uparrow \end{array} \right| \end{aligned}$$


and

$$\begin{aligned}
\bar{H}_{-1,B} &:= \text{ev}_B \left(\frac{\tilde{c}_0(\tilde{D}_{-1}^{(1)})}{i v_{-1}^*} \right) = \sum_{i=1}^{N-1} \sum_{j=i+1}^N P_{(j+1 \dots i)}(\mathbf{x}^*)^{-1} h_{j-1,j}(x_i^* - x_j^*) P_{(j+1 \dots i)}(\mathbf{x}^*) \\
(4.43) \quad &= \sum_{i < j}^N \bar{a} \quad \dots \quad \begin{array}{c} x_1^* \dots x_i^* \dots x_j^* \dots x_N^* \\ \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \\ \text{Diagram with crossings and a central dot} \\ \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \\ x_1^* \dots x_i^* \dots x_j^* \dots x_N^* \end{array} \quad .
\end{aligned}$$

Since $\bar{H}_{\pm 1,B} \propto H_{\pm 1,B}$, by (4.40) they commute,

$$(4.44) \quad [\bar{H}_{1,B}, \bar{H}_{-1,B}] = 0.$$

We stress that both the classical equilibrium positions $\mathbf{x}^* = B \cdot \mathbf{x}^{*(1)}$ and the parameters depend on $B \in \text{PSL}(2, \mathbb{Z})$, while the classical equilibrium momenta $\mathbf{p}^*$ dropped out thanks to (4.41). The form (4.42) for the hamiltonian of an integrable q -deformed long-range spin chain was first found in [Lam18], and (4.43) in [LPS22].

One proceeds similarly for higher hamiltonians, with the explicit result looking more and more involved. Let us illustrate this for $n = 2$. The operator $\tilde{D}_2$ from (2.20) takes

$$\begin{aligned}
\tilde{D}_2 &= \sum_{j < j'}^N A_{\{j,j'\}}(\mathbf{x}) P_{\{j,j'\}}(\mathbf{x})^{-1} \Gamma_j \Gamma_{j'} P_{\{j,j'\}}(\mathbf{x}) \\
(4.45) \quad &= \sum_{j < j'}^N A_{\{j,j'\}}(\mathbf{x}) \times \begin{array}{c} x_1 \dots x_j \dots x_{j'} \dots x_N \\ \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \\ \text{Diagram with crossings and a central dot} \\ \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \\ x_1 \dots x_j \dots x_{j'} \dots x_N \end{array} \quad \dots \\
&= \sum_{j < j'}^N A_{\{j,j'\}}(\mathbf{x}) P_{\{j,j'\}}(\mathbf{x})^{-1} P_{\{j,j'\}}(\mathbf{x} - i\epsilon \hbar (\mathbf{e}_j + \mathbf{e}_{j'})) \Gamma_j \Gamma_{j'},
\end{aligned}$$

where $\{\mathbf{e}_j\}_j$ is the standard orthonormal basis of $\mathbb{C}^N$, so that by (B.7) we have

$$\begin{aligned}
(4.46) \quad P_{\{j,j'\}}(\mathbf{x} - i\epsilon \hbar (\mathbf{e}_j + \mathbf{e}_{j'})) &= P_{(2 \dots j')}(\text{gray } x_j - i\epsilon \hbar, x_1, \dots, x_{j-1}, x_{j+1}, \dots, x_{j'} - i\epsilon \hbar, \dots, x_N) \\
&\quad \times P_{(1 \dots j)}(x_1, \dots, x_{j-1}, x_j - i\epsilon \hbar, x_{j+1}, \dots, x_{j'} - i\epsilon \hbar, \dots, x_N),
\end{aligned}$$

where the arguments that do not actually appear in any R -matrix are printed in gray.

Working out the $\hbar$ -expansion of (4.45) we see that $\tilde{D}_2^{(0)} = D_2 \text{id}$, like for $n = 1$. At first order in $\hbar$ there are two types of contributions. When expanding the argument with x_j , the other line can simply be straightened out using the unitarity relation (2.13), giving a contribution whose summands resemble the spin operators appearing in $\tilde{D}_1^{(1)}$:

$$(4.47) \quad (i\epsilon)^2 \sum_{j < j'}^N A_{\{j,j'\}}(\mathbf{x}) \sum_{i=1}^{j-1} P_{(i+1 \dots j)}(\mathbf{x})^{-1} h_{i,i+1}(x_i - x_j) P_{(i+1 \dots j)}(\mathbf{x}) \Gamma_j \Gamma_{j'}.$$

When we expand the argument with $x_{j'}$ we obtain a more complicated nested product:

$$\begin{aligned}
(4.48) \quad & (i\epsilon)^2 \sum_{j < j'}^N A_{\{j, j'\}}(\mathbf{x}) \sum_{i=1}^{j-1} P_{(i \dots j)}(\mathbf{x})^{-1} P_{(i+2 \dots j')} (s_{(i \dots j)} \cdot \mathbf{x})^{-1} h_{i+1, i+2}(x_i - x_{j'}) \\
& \times P_{(i+2 \dots j')} (s_{(i \dots j)} \cdot \mathbf{x}) P_{(i \dots j)}(\mathbf{x}) \Gamma_j \Gamma_{j'} \\
& + (i\epsilon)^2 \sum_{j < j'}^N A_{\{j, j'\}}(\mathbf{x}) \sum_{i=j+1}^{j'-1} P_{(i+1 \dots j')}(\mathbf{x})^{-1} h_{i, i+1}(x_i - x_{j'}) P_{(i+1 \dots j')}(\mathbf{x}) \Gamma_j \Gamma_{j'},
\end{aligned}$$

where

$$(4.49) \quad s_{(i \dots j)} \cdot \mathbf{x} = (x_1, \dots, x_{i-1}, x_j, x_i, \dots, x_{j-1}, x_j, x_{j+1}, \dots, x_{j'}, x_{j'+1}, \dots, x_N),$$

again with in gray all coordinates that do not actually appear as the argument of any R -matrix contained in $P_{(i+2 \dots j')}$. The last line of (4.48) has the same structure as (4.47), while the spin operators in the first two lines of (4.48) correspond to

$$(4.50) \quad \begin{array}{c} x_1 \quad x_i \quad \dots \quad x_j \quad \dots \quad x_{j'} \quad x_N \\ \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \\ \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \\ \bar{a} \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \\ \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \\ x_1 \quad x_i \quad \dots \quad x_j \quad \dots \quad x_{j'} \quad x_N \end{array}.$$

Now note that

$$(4.51) \quad A_{j, j'} = A_j A_{j'} \frac{-\theta(x_j - x_{j'})^2}{\theta(x_j - x_{j'} + \eta) \theta(x_j - x_{j'} - \eta)},$$

such that, upon taking the classical limit and evaluating at B ,

$$\begin{aligned}
(4.52) \quad \bar{H}_{2, B} &:= \text{ev}_B \left(\frac{\tilde{c}_0(\tilde{D}_2^{(1)})}{(i v_1)^2} \right) \\
&= \sum_{i < j}^N \left(\sum_{\substack{k=1 \\ k \notin \{i, \dots, j\}}}^N \frac{-\theta(x_j^* - x_k^*)^2}{\theta(x_j^* - x_k^* + \eta) \theta(x_j^* - x_k^* - \eta)} \right) P_{(i+1 \dots j)}(\mathbf{x}^*)^{-1} \\
&\quad \times h_{i, i+1}(x_i^* - x_j^*) P_{(i+1 \dots j)}(\mathbf{x}^*) \\
&+ \sum_{i < j < k}^N \frac{-\theta(x_j^* - x_k^*)^2}{\theta(x_j^* - x_k^* + \eta) \theta(x_j^* - x_k^* - \eta)} P_{(i \dots j)}(\mathbf{x}^*)^{-1} P_{(i+2 \dots k)}((s_{(i \dots j)} \cdot \mathbf{x})^*)^{-1} \\
&\quad \times h_{i+1, i+2}(x_i^* - x_k^*) P_{(i+2 \dots k)}((s_{(i \dots j)} \cdot \mathbf{x})^*) P_{(i \dots j)}(\mathbf{x}^*)
\end{aligned}$$

The first line matches the $n = 1$ hamiltonian (4.42), except that the summands are weighed differently. The second line is new to $n = 2$. The form of this spin-chain hamiltonian is compatible with that of the second hamiltonians from [LPS22] and appeared more explicitly in [MZ23b].

Just like $\bar{H}_{\pm 1, B}$ from (4.42)–(4.43) are related by left-right flipping the diagram, $\bar{H}_{-2, B}$ is obtained from $\bar{H}_{2, B}$ by a vertical reflection of the diagrammatic representation. One can continue this procedure to generate explicit expressions for the higher hamiltonians $H_{n, B}$, until one reaches the ‘equator’ $n \sim N/2$.

In conclusion, at any fixed classical equilibrium configuration $(\mathbf{x}^*, \mathbf{p}^*) = B \cdot (\mathbf{x}^{*(1)}, \mathbf{p}^{*(1)}) \in M_{\mathbb{C}}^*$ (parametrised by $B \in PSL(2, \mathbb{Z})$), we thus obtain a hierarchy of commuting spin-chain

building on [MV24, LRS24, Cha24], to derive a quantum spin chain with long-range interactions by freezing. We proved that quantum integrability is preserved in the sense that if the $\tilde{D}_n$ commute among each other, then so do the spin-chain hamiltonians $H_{n,B}$ defined in (4.33), frozen at the equilibrium labelled by $B \in \text{PSL}(2, \mathbb{Z})$.

The vertex- and face-type cases from [MZ23b] and [KL24] give rise to two separate landscapes of long-range spin chains that only overlap in a single point [KL25], see especially Figures 2–3 therein. In particular, our results allow one to freeze at $B = S$, which (unlike $B = 1$) provides spin chains admitting a short-range limit. Our results also carry over to the (trigonometric) long-range limit, and, in the face case, for $q \rightarrow 1$ agree with [Cha24], and §9 of [LRS24]. Besides proving integrability, we believe that freezing holds the key to a complete understanding of these q -deformed long-range spin chains—including exact descriptions of their spectra, like for the (face-type) Haldane–Shastry chain [BGHP93, LS24] and its q -deformation [Ugl95, LPS22]. Finally, it would be interesting to know whether any of the quantum many-body systems with spins discussed in this paper, or any of their limits, can be obtained from the double elliptic (‘DELL’) system with spins that was proposed in [KS20], or if they are related to the new spin–Calogero–Sutherland models recently introduced in [BM24, HLYZ24].

ACKNOWLEDGEMENTS

We thank O. Chalykh, M. Mikhailov, J. Pulmann and M. Volk for discussions, and A. Bourget for correspondence. Rob Klabbers’s research is funded by the Deutsche Forschungsgemeinschaft (DFG, German Research Foundation) - Projektnummer 417533893/GRK2575 “Rethinking Quantum Field Theory”.

APPENDIX A. ELLIPTIC PRELIMINARIES

A.1. Elliptic functions. We summarise our conventions for the elliptic functions we use and list their most important properties. Standard references are [OOL⁺, AS48, WW02].

The odd Jacobi theta function with lattice parameter $\tau \in \mathbb{C}$ ($\text{Im } \tau > 0$) is defined as

$$\begin{aligned} \vartheta(x|\tau) &= 2 \sum_{n=0}^{\infty} (-1)^n p^{(n+1/2)^2} \sin[(2n+1)x] \\ &= 2p^{1/4} \sin(x) \prod_{n=1}^{\infty} (1 - p^{2n})(1 - e^{2ix}p^{2n})(1 - e^{-2ix}p^{2n}), \end{aligned} \quad p = e^{i\pi\tau}, \quad (\text{A.1})$$

where p is called the ‘nome’. The normalised theta function $\theta(x) = \vartheta(\pi x)/(\pi \vartheta'(x))$ is odd and entire as well as is doubly quasiperiodic, $\theta(x+1) = -\theta(x)$ and $\theta(x+\tau) = -p^{-1}e^{-2\pi ix}\theta(x)$, with a simple zero at the origin, and satisfies $\theta'(0) = 1$. Its trigonometric and rational degenerations are $\theta(x) = \sin(\pi x)/\pi + O(p)$ and $\sin(\pi x)/\pi = x + O(N^{-2})$. It obeys the addition formula

$$\begin{aligned} \theta(x+y)\theta(x-y)\theta(z+w)\theta(z-w) &= \theta(x+z)\theta(x-z)\theta(y+w)\theta(y-w) \\ &\quad + \theta(x+w)\theta(x-w)\theta(z+y)\theta(z-y). \end{aligned} \quad (\text{A.2})$$

Other standard Jacobi theta functions are defined in terms of (A.1) by

$$\begin{aligned} \vartheta_1(z|\tau) &= \vartheta(z), & \vartheta_2(z|\tau) &= \vartheta(z+1/2|\tau), \\ \vartheta_3(z|\tau) &= e^{i\pi\tau/4}e^{i\pi x}\vartheta(z+(1+\tau)/2|\tau), & \vartheta_4(z|\tau) &= -ie^{i\pi\tau/4}e^{i\pi x}\vartheta(z+\tau/2|\tau), \end{aligned} \quad (\text{A.3})$$

hence one can think of these as (rescaled) versions of the odd Jacobi theta function (A.1) shifted by half-periods of the lattice, generalising the well-known identity $\cos(x) = \sin(x+\pi/2)$ between the elementary trigonometric functions. Expanding in the nome p we find

$$\begin{aligned} p^{-1/4}\vartheta_1(z|\tau) &= 2\sin \pi x + O(p^2), & p^{-1/4}\vartheta_2(z|\tau) &= 2\cos \pi x + O(p^2), \\ \vartheta_3(z|\tau) &= 1 + 2p\cos \pi x + O(p^2), & \vartheta_4(z|\tau) &= 1 - 2p\cos \pi x + O(p^2). \end{aligned} \quad (\text{A.4})$$

There are many more relations between the ϑ_a , for our purposes the Jacobi imaginary transformation will be particularly important. For a given τ let $\tau' = -1/\tau$, then the following relations hold

$$\begin{aligned}
(A.5) \quad & i(-i\tau)^{1/2} \vartheta_1(z|\tau) = e^{i\tau' z^2/\pi} \vartheta_1(\tau' z|\tau'), \\
& (-i\tau)^{1/2} \vartheta_2(z|\tau) = e^{i\tau' z^2/\pi} \vartheta_4(\tau' z|\tau'), \\
& (-i\tau)^{1/2} \vartheta_3(z|\tau) = e^{i\tau' z^2/\pi} \vartheta_3(\tau' z|\tau'), \\
& (-i\tau)^{1/2} \vartheta_4(z|\tau) = e^{i\tau' z^2/\pi} \vartheta_2(\tau' z|\tau'),
\end{aligned}$$

effectively relating the two regimes in which $\text{Im}(\tau)$ is either large or small. Note that ϑ_2 and ϑ_4 switch places under this transformation, whereas ϑ_1 and ϑ_3 transform into themselves.

The (normalised) Kronecker elliptic function is

$$\begin{aligned}
(A.6) \quad \phi(u, v|\tau) &:= \frac{\theta(u+v|\tau)}{\theta(u|\tau)\theta(v|\tau)} = \frac{\pi \sin(\pi(u+v))}{\sin(\pi u) \sin(\pi v)} + O(p) \\
&= \pi(\cot(\pi u) + \cot(\pi v)) + O(p).
\end{aligned}$$

If no confusion can arise we will suppress its dependence on τ , simply writing $\phi(u, v)$. This function is symmetric and doubly (quasi)periodic, $\phi(u+1, v) = \phi(u, v)$ and $\phi(u+\tau, v) = e^{-2\pi i v} \phi(u, v)$.

A.2. Elliptic R -matrices. In the following, for $1 \leq \alpha, \beta \leq r$ let $E_{\alpha\beta} \in \text{Mat}(r \times r, \mathbb{C})$ denote the $r \times r$ matrix units, with entries $(E_{\alpha\beta})_{\gamma\delta} = \delta_{\alpha\gamma} \delta_{\beta\delta}$.

A.2.1. Vertex-type. For $r \geq 2$ the Baxter–Belavin R -matrix for $\mathfrak{gl}_r$ can be given as

$$(A.7a) \quad R(x; \eta|\tau) := \sum'_{\alpha, \beta, \gamma, \delta=1}^r R_{\alpha\gamma, \beta\delta}(x; \eta|\tau) E_{\alpha\beta} \otimes E_{\gamma\delta},$$

where the prime indicates that sum is restricted to the ‘weakened ice rule’ $\alpha + \gamma \equiv \beta + \delta \pmod{r}$, and the nonzero entries read

$$\begin{aligned}
(A.7b) \quad R_{\alpha\gamma, \beta\delta}(x; \eta|\tau) &:= \frac{1}{\phi(x, \eta|\tau)} \exp\left(\frac{2\pi i}{r}((\beta - \alpha)x + (\gamma - \beta)\eta + (\gamma - \beta)(\gamma - \alpha)\tau)\right) \\
&\quad \times \phi(x + \gamma - \beta\tau, \eta + (\beta - \alpha)\tau|r\tau)
\end{aligned}$$

Then $\check{R}(x) = P R(x)$ again satisfies the relations (2.6)–(2.8) as well as (2.11). The Baxter–Belavin R -matrix is also commonly written in terms of a representation of the Heisenberg group [Bel81]; for this and many further relations see e.g. the appendix of [ZZ22].⁹

For $r = 2$ the weakened ice rule allows for $R_{11,22}, R_{22,11} \neq 0$ in addition to nonzero entries in the same six positions as for the dynamical R -matrix and this definition yields the eight-vertex R -matrix in the conventions of [KL25], see Section 2.1 therein. The trigonometric limit gives the usual (symmetric) six-vertex R -matrix in the ‘principal grading’ (possibly up to a global spin rotation), see §B.2 in [KL25].

A.2.2. Face-type. The elliptic dynamical R -matrix of type $\mathfrak{gl}_r$ with $r \geq 2$ reads [Fel95b, FV97]

$$\begin{aligned}
(A.8) \quad R(x, a; \eta|\tau) &:= \sum_{\alpha=1}^r E_{\alpha\alpha} \otimes E_{\alpha\alpha} + \frac{1}{\phi(x, \eta|\tau)} \sum_{\alpha \neq \beta}^r \phi(a_\beta - a_\alpha, \eta|\tau) E_{\alpha\alpha} \otimes E_{\beta\beta} \\
&\quad + \frac{1}{\phi(x, \eta|\tau)} \sum_{\alpha \neq \beta}^r \phi(x, a_\beta - a_\alpha|\tau) E_{\alpha\beta} \otimes E_{\beta\alpha}.
\end{aligned}$$

Then $\check{R}(x, a) := P R(x, a)$ satisfies the unitarity relation (2.6), the (dynamical) Yang–Baxter equation (2.7), ‘commutativity at a distance’ (2.8), as well as the initial condition (2.11). For

⁹ Our η is related to that of (B.14) in [ZZ22] via $\eta_{ZZ} := \eta/r$.

a graphical interpretation, including the connection to the ‘interaction (a)round the face’ (IRF) picture, see §B in [KL24]. This R -matrix is associated to the elliptic quantum group $E_{\tau,\eta}(\mathfrak{gl}_r)$ [FV97].

For $r = 2$, (A.8) coincides with the dynamical R -matrix in [KL25] and [KL24] after identifying $a = a_1 - a_2$.¹⁰ Taking the trigonometric, and then non-dynamical limit, one obtains the trigonometric R -matrix in the ‘homogeneous grading’, related to the Hecke algebra, see e.g. §5.1 of [KL24].

A.2.3. Face-vertex transformation. The face- and vertex-type elliptic R -matrices are related by a ‘face-vertex transformation’ [Bax73, FV96], which can be interpreted as a Drinfeld twist [JKOS99]. As we emphasised in §5.2 of [KL25], this transformation does *not* extend from the level of the R -matrix to a simple conjugation of the corresponding spin-Ruijsenaars models, yielding very different spectral and physical properties.

APPENDIX B. DEFORMED SPIN PERMUTATIONS

In this appendix we provide more details for the deformed spin permutations defined in §2.1.

Let $w \mapsto s_w$ denote the natural action of S_N on $\text{Fun}(\mathbf{x})$ by permuting variables. According to (2.6)–(2.8), $\tilde{s}_i := s_{i,i+1} P_{i,i+1}(x_i - x_{i+1})$ gives an S_N -action on $\text{Fun}(\mathbf{x}) \otimes V^{\otimes N}$ [Fel95a], see also [FWZJ16]. By (2.11) it deforms the diagonal action. Write $w \mapsto \tilde{w}$ for this representation. Define $P_w(\mathbf{x})$ by $\tilde{w} = s_w P_w(\mathbf{x})$. Then considering $\tilde{w}\tilde{w}' = \tilde{w}\tilde{w}'$ yields the general cocycle condition¹¹

$$(B.1) \quad P_{ww'}(\mathbf{x}) = s_{w'}^{-1} P_w(\mathbf{x}) s_{w'} P_{w'}(\mathbf{x}) = P_w(s_{w'}^{-1} \cdot \mathbf{x}) P_{w'}(\mathbf{x}).$$

This includes the cocycle condition (2.16) as the special case $w' = (i \ i + 1)$, which allows one to recursively construct any $P_w(\mathbf{x})$ starting from the identity operator (2.15).

B.1. Cycles. The spin-Ruijsenaars operators $\tilde{D}_n$ from (2.20) and (2.22) are all built from deformed cycles. Here are some examples. Clearly,

$$(B.2) \quad P_{(i,i+1)}(\mathbf{x}) = P_{i,i+1}(x_i - x_{i+1}) = \begin{array}{c} x_1 \quad \dots \quad x_{i+1} \quad x_i \quad \dots \quad x_N \\ \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \\ \bar{a} \quad \quad \quad \dots \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \\ x_1 \quad \quad \quad \quad \quad \quad x_i \quad x_{i+1} \quad \quad \quad x_N \end{array}.$$

Next, for $(i \ i + 1 \ i + 2) = (i \ i + 1)(i + 1 \ i + 2)$ we get

$$(B.3) \quad P_{(i \ i + 1 \ i + 2)}(\mathbf{x}) = P_{i,i+1}(x_i - x_{i+2}) P_{i+1,i+2}(x_{i+1} - x_{i+2}) = \begin{array}{c} x_1 \quad \dots \quad x_{i+2} \quad x_i \quad x_{i+1} \quad \dots \quad x_N \\ \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \\ \bar{a} \quad \quad \quad \dots \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \\ x_1 \quad \quad \quad \quad \quad \quad x_i \quad x_{i+1} \quad x_{i+2} \quad \quad \quad x_N \end{array}.$$

More generally, for $k < l$ the (uninterrupted) cycle $(k \ k + 1 \ \dots \ l) = (k \ k + 1) \cdots (l - 1 \ l)$ yields

$$(B.4) \quad P_{(k \ k + 1 \ \dots \ l)}(\mathbf{x}) = P_{k,k+1}(x_k - x_l) \cdots P_{l-1,l}(x_{l-1} - x_l) = \begin{array}{c} x_1 \quad \dots \quad x_l \quad x_k \quad \dots \quad x_{l-1} \quad \dots \quad x_N \\ \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \\ \bar{a} \quad \quad \quad \dots \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \\ x_1 \quad \quad \quad \quad \quad \quad x_k \dots x_{l-1} \quad x_l \quad \quad \quad x_N \end{array}.$$

The case $k = 1, l = i$ gives (2.18).

In fact, as these examples illustrate, one can compute $P_w(\mathbf{x})$ graphically. First draw $w \in S_N$: start with a row of numbers $1 \ 2 \ \dots \ N$, a little above it $w(1) \ w(2) \ \dots \ w(N)$, and connect equal numbers, drawing so that no more than two lines cross at any point. Remove unnecessary double crossings, anticipating (2.13), to get a reduced decomposition of w . Now replace all i

¹⁰ One obtains the dynamical R -matrix of [ZZ22] after a transposition and passing to $\eta_{ZZ} := \eta/r$.

¹¹ Alternatively, one can set $\tilde{w} = P'_w(\mathbf{x}) s_w$ and work with $P'_w(\mathbf{x}) = s_w P_w(\mathbf{x}) s_w^{-1} = P_w(s_w \cdot \mathbf{x})$; in particular, $P'_{(i \ i + 1)}(\mathbf{x}) = P_{i,i+1}(x_{i+1} - x_i)$.

by x_i in both rows and reinterpret the crossings as deformed permutations via (2.12). For instance, if again $k < l$ we may compute

$$(B.5) \quad P_{(l-1 \dots k)}(\mathbf{x}) = P_{l-1,l}(x_k - x_l) \cdots P_{k,k+1}(x_k - x_{k+1}) = \bar{a} \begin{array}{c} x_1 \quad \quad x_{k+1} \dots x_l \quad x_k \quad \quad x_N \\ \uparrow \quad \quad \uparrow \quad \quad \uparrow \quad \quad \uparrow \quad \quad \uparrow \\ \begin{array}{c} \text{Diagram with crossings between lines } x_k \text{ and } x_{k+1} \dots x_l \\ \text{and } x_l \text{ and } x_k \end{array} \\ \uparrow \quad \quad \uparrow \quad \quad \uparrow \\ x_1 \quad \quad x_k \quad x_{k+1} \dots x_l \quad \quad x_N \end{array},$$

by first drawing the diagram on the right and then reading off the expression in the middle.¹² The case $k = i$, $l = N$ yields (2.19).

B.2. Grassmannian permutations. We are particularly interested in *Grassmannian permutations*, which are minimal-length representatives of the coset $S_N/(S_n \times S_{N-n})$ for some $1 \leq n \leq N$, i.e. permutations with (at most) one descent $w(n) > w(n+1)$. More explicitly, given an n -element subset $I = \{i_1 < \dots < i_n\} \subseteq \{1, \dots, N\}$, the corresponding Grassmannian permutation, which we denote by $w_I \in S_N$, sends $k \mapsto i_k$ for all $1 \leq k \leq n$ without permuting either $\{1, \dots, n\}$ or $\{n+1, \dots, N\}$ amongst each other. It can be defined recursively, starting from $w_\emptyset = e$ the identity, through the recursion relation

$$(B.6) \quad w_{J \cup \{j\}} = w_J (j \ j-1 \dots |J|+1) \quad \text{if } j > \max(J).$$

For instance, $n = 1$ gives the cycle $w_{\{i\}} = (i \ i-1 \dots 1)$, at $n = 2$ we get the product of cycles $w_{\{i, i'\}} = (i \ i-1 \dots 1) (i' \ i'-1 \dots 2)$, and so on. In general, $w_I = (i_1 \ i_1-1 \dots 1) \cdots (i_n \ i_n-1 \dots n)$. Note that at $n = N$ we simply retrieve $w_{\{1, \dots, N\}} = e$ the identity. This motivates further defining $w_{-I} := w_{\{1, \dots, N\} \setminus I}$. For example, $w_{-\{i\}} = w_{\{1, \dots, i-1, i+1, \dots, N\}} = (i \ i+1 \dots N)$ is again a cycle, $w_{-\{i, i'\}} = (i \ i+1 \dots N-1) (i' \ i'+1 \dots N)$ a product of two cycles, and in general $w_{-I} = (i_1 \ i_1+1 \dots N-n+1) \cdots (i_n \ i_n+1 \dots N)$.

From these w_I we finally construct the operators $P_I(\mathbf{x}) := P_{w_I^{-1}}(\mathbf{x})$ as in (2.17). Note the inverse! Let us again give a few examples. $P_\emptyset(\mathbf{x})$ is just (2.15). For $n = 1$ we get (2.18). Next,

$$(B.7) \quad P_{\{i, i'\}}(\mathbf{x}) = P_{(2 \dots i'-1 \ i')}(x_i, x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_N) P_{(1 \dots i-1 \ i)}(\mathbf{x})$$

$$= \bar{a} \begin{array}{c} x_i \quad x_{i'} \quad x_1 \dots x_{i-1} \quad \quad x_N \\ \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \\ \begin{array}{c} \text{Diagram with crossings between lines } x_i \text{ and } x_{i'} \\ \text{and } x_{i-1} \text{ and } x_i \end{array} \\ \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \\ x_1 \dots x_{i-1} \quad x_i \quad x_{i'} \quad \quad x_N \end{array}.$$

Finally, since $w_{\{1, \dots, N\}} = e$ the first nontrivial example of $P_{-I}(\mathbf{x}) := P_{\{1, \dots, N\} \setminus I}(\mathbf{x})$ is (2.19).

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¹² Observe that (B.5) is not quite the inverse of (B.4) since the mismatch in inhomogeneities does not allow for composition. Rather, the inverse $P_w(\mathbf{x})^{-1} = P_{w^{-1}}(x_{w(1)}, \dots, x_{w(N)})$ is graphically obtained by flipping the diagram of $P_w(\mathbf{x})$ upside down and reversing the orientations of all lines back from bottom to top.

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