## Differentialgeometrie I

Exercise sheet 3

## Exercise 1.

(a) Compute the first and second fundamental forms of a graph and determine its Christoffel symbols both extrinsically (i.e. by using the definition) as well as intrinsically (i.e. with Theorem 3.5).
(b) Compute the matrix $\left(L_{i j}\right)$ describing the second fundamental form of a rotation surface and show that $\operatorname{det}\left(L_{i j}\right)$ is vanishing if and only if every meridian is a straight line.
Hint: In Exercise 2 of Sheet 2 we have computed its metric coefficients. Try to visualize the second statement in a picture.

## Exercise 2.

Consider the 2-sphere $S^{2}$ (without the zero meridian) parametrized as in the lecture by

$$
x(\theta, \varphi)=(\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)
$$

(a) Calculate the metric tensor, its inverse matrix, the coefficients $L_{i j}$ of the second fundamental form and the Christoffel symbols $\Gamma_{i j}^{k}$. Justify geometrically why none of these quantities depend on $\varphi$.
Let $\gamma$ be a curve parametrized by arc length with trace on $S^{2}$.
(b) The normal curvature $k_{n}$ of $\gamma$ is constant. What is its value? Does it depend on the radius of the sphere?
(c) If the geodesic curvature $k_{g}$ of $\gamma$ is constant then $\gamma$ is a circle.
(d) If $\gamma$ is a geodesic then $\gamma$ is a great circle.
(e) Determine the geodesic curvature of a latitudinal circle.

Hint: In case you are missing the proper education in geography, a latitudinal circle is in the above parametrization given by $\varphi \mapsto x\left(\theta_{0}, \varphi\right)$ for a fixed value $\theta_{0}$. For all these exercises I suggest (in addition to your other arguments) to create instructive sketches visualizing the situation.

## Exercise 3.

(a) Let $M$ be a surface and $E$ a plane in $\mathbb{R}^{3}$ that intersects $M$ in a curve $\gamma$. Then $\gamma$ is a geodesic if $E$ is a symmetry plane of $M$.
(b) Every straight line in $\mathbb{R}^{3}$ contained in a surface $M$ is a geodesic.
(c) Let $M_{1}$ be the surface $\left\{x^{2}+y^{2}-z^{2}=1\right\}$ and $M_{2}$ the surface $\left\{z=x^{2}-y^{2}\right\}$. Draw detailed pictures of $M_{1}$ and $M_{2}$ and describe geodesics on $M_{1}$ and $M_{2}$.

## Exercise 4.

Consider the upper half plane

$$
\mathbb{R}_{+}^{2}=\left\{(x, y) \in \mathbb{R}^{2} \mid y>0\right\}
$$

with the so-called hyperbolic metric given by $g_{11}=g_{22}=1 / y^{2}, g_{12}=g_{21}=0$. We will show in the second part of the lecture that it is impossible to realize $\mathbb{R}_{+}^{2}$ with that metric as a surface in $\mathbb{R}^{3}$. Nevertheless all intrinsic calculations can be carried out with respect to this metric.
(a) Compute the Christoffel symbols.
(b) Determine the geodesics $\gamma$ and $\alpha$ with

$$
\begin{aligned}
\left(\gamma^{1}(0), \gamma^{2}(0)\right) & =\left(x_{0}, 1\right), \\
\left(\left(\gamma^{1}\right)^{\prime}(0),\left(\gamma^{2}\right)^{\prime}(0)\right) & =(0,1), \\
\left(\alpha^{1}(0), \alpha^{2}(0)\right) & =(a, r), \text { and } \\
\left(\left(\alpha^{1}\right)^{\prime}(0),\left(\alpha^{2}\right)^{\prime}(0)\right) & =(r, 0)
\end{aligned}
$$

Find explicit parametrizations of $\gamma$ and $\alpha$ and describe both geometrically in $\mathbb{R}_{+}^{2}$.
(c) Let $X_{0}=(0,1)$ be a tangent vector at the point $(0,1)$ of $\mathbb{R}_{+}^{2}$. Verify that $X_{0}$ is a unit vector in $T_{(0,1)} \mathbb{R}_{+}^{2}$ with respect to the hyperbolic metric. Let $X(t)$ be the parallel transport of $X_{0}$ along the curve $x=t, y=1$. Show that the angle between $X(t)$ and the $y$-axis is equal to $t$.

## Exercise 5.

Determine the transformation behavior of the second fundamental form $L_{i j}$ and the Christoffel symbols $\Gamma_{i j}^{k}$ under a coordinate transformation.

