WS 2022/23

Differentialgeometrie I

Exercise sheet 9

Exercise 1.

- (a) Show that the antipodal map $-id: S^n \to S^n$ is an isometry and use this to construct a Riemannian metric on $\mathbb{R}P^n$ such that the quotient map $\pi: S^n \to \mathbb{R}P^n$ is a local isometry.
- (b) Construct the *flat* Riemmanian metric on the *n*-torus as in the lecture.
- (c) Show that the quotient of \mathbb{R}^2 under the antipodal map is homeomorphic to \mathbb{R}^2 .
- (d) Show that the quotient of \mathbb{R}^3 under the antipodal map is not homeomorphic to a manifold.
- (e) Can you generalize the statement from (a) and (b) to more general settings?

Exercise 2.

Let M_1 and M_2 be Riemannian manifolds. Construct from this a natural Riemannian metric on $M_1 \times M_2$. Use this to construct a Riemannian metric on the *n*-torus T^n and show that this metric is isometric to the flat metric on T^n constructed in the lecture (see Exercise 1 (b)).

Exercise 3.

(a) Let $f: M \to N$ be an immersion and let g be a Riemannian metric on N. If f would be an embedding then we have defined the induced Riemannian metric f^*g in the lecture. Show that for an immersion the same construction yields a Riemannian metric on M. Then

$$f\colon (M, f^*g) \to (N, g)$$

is called an **isometric immersion**.

(b) Describe an isometric immersion of the flat *n*-torus T^n into \mathbb{R}^{2n} .

Exercise 4.

We consider the map $f: S^2 \to \mathbb{R}^4$ given by

$$(x, y, z) \longmapsto (x^2 - y^2, xy, xz, yz).$$

Show that f induces an embedding of $\mathbb{R}P^2$ into \mathbb{R}^4 . Compute the metric coefficients and the Christoffel symbols of the by f induced metric in a suitable atlas of $\mathbb{R}P^2$.

Exercise 5.

Let (M, g) be a Riemannian manifold. The unit tangent bundle is

$$T^1M:=\bigcup_{p\in M}\left\{X\in T_pM\big|g_p(X,X)=1\right\}\subset TM.$$

- (a) T^1M is again a smooth manifold. What is its dimension?
- (b) If M is compact then T^1M is compact.
- (c) Determine the diffeomorphism type of the unit tangent bundle of S^1 and \mathbb{R}^n .
- (d) Show that T^1S^2 is diffeomorphic to SO(3). Hint: Consider the map

$$SO(3) \times S^2 \longrightarrow S^2$$
$$(A, x) \longmapsto A \cdot x$$

Exercise 6.

(a) Prove Lemma 6.4: Let Y_1 and Y_2 vector fields that agree on an open neighborhood of $p \in M$ and let X be another vector field on M. Then

$$(\nabla_X Y_1)(p) = (\nabla_X Y_2)(p)$$

(b) Show that the covariant derivative from the first part of the lecture defines a covariant derivative with respect to the definition from Chapter 6. Generalize the definition for surfaces in \mathbb{R}^3 from the first part of the lecture to a general Riemmanian submanifold.

Exercise 7.

Let $\mathbb{H}^n = \{(x_1, \dots, x_n) \in \mathbb{R}^n | x_n > 0\}$ denote the upper half space model of the hyperbolic space with its standard Riemannian metric

$$g_x(v_1, v_2) = \frac{\langle v_1, v_2 \rangle}{x_n^2},$$

where $v_1, v_2 \in T_x \mathbb{H}^n \cong \mathbb{R}^n$ and $\langle \cdot, \cdot \rangle$ denotes the standard Euclidean inner product. Calculate the metric coefficients and the Christoffel symbols with respect to the canonical global coordinate chart $\phi \colon \mathbb{H}^n \to V \subset \mathbb{R}^n$ given by $\phi(x) = x$.